

GEETHANJALI INSTITUTE OF SCIENCE & TECHNOLOGY: NELLORE (AUTONOMOUS)

NELLORE-524317 (A.P) INDIA

B.TECH IN MECHANICAL ENGINEERING (ACCREDITATED BY NBA) COURSE STRUCTURE AND SYLLABI UNDER RG 22 REGULATIONS



Mechanical Engineering IV B.TECH Semester-VII (Theory-6, Skill Course-1) S.No Course **Course Name** Category Hours per week **Credits** Code L T P PEC 0 1. 22A0332T 0 3 **Professional Elective Course -III** 3 22A0332Ta Design of Heat Transfer Equipment Tribology 22A0332Tb Unconventional Machining 22A0332Tc Processes 2. 22A0333T **Professional Elective Course -IV** 3 0 0 3 PEC 22A0333Ta Refrigeration and Air-Conditioning 22A0333Tb Introduction to Robotics 22A0333Tc Finite Element Methods **3.** 22A0334T 0 0 3 **Professional Elective Course-V** PEC 3 22A0334Ta Power Plant Engineering 22A0334Tb Non-Destructive Evaluation 22A0334Tc Fundamentals of Drone Technology 4. OEC **Open Elective Course -III** 3 0 0 3 22A0151T Disaster Management 22A0241Ta Smart Electric Grid 22A0433T Industrial Electronics 22A0529T Cloud Computing OEC 0 5. **Open Elective Course -IV** 3 0 3 22A0152T Construction Management 22A0332Ta **Electric Vehicles** 22A0432T Basics of VLSI Design 22A0534Tb Introduction to Cyber Security 22A0335T PCC 6. 2 1 0 3 **Operations Research** 7. 22A0336P SAC 1 0 2 2 **Skill Advanced Course** Industrial Automation 8. 22A0337 Internship-II(Evaluated the Industry Internship completed at the 3 end of Third year) 23 Total

Distribution of Credits among the Category of Courses							
S.No	Category of Courses Introduced	Credits Assigned					
1	Professional Core Courses (1T)	3					
2	Professional Elective Courses (3T)	9					
3	Open Elective Course Courses (2T)	6					
4	Skill Advanced Course – 1 (T+P)	2					
5	Summer Internship of completed in Third year	3					
	Total Credits	23					



Mechanical Engineering IV B.TECH

Semester-VIII								
S.No. Course	Course Name	Hou	Hours per week					
	Code		L	Τ	P			
1	22A0338	Full Internship/Project work	0	0	24	12		
Total Credits								

Distribution of Credits among the Category of Courses						
S.No	Category of Courses Introduced	Credits Assigned				
1	Project Work	12				
	Total Credits	12				
	Overall Credits in the Program	163				

COURSES OFFERED FOR HONOURS DEGREE IN MECHANICAL ENGINEERING

Note: 1. The Honours subjects are having a total of 20 additional credits.

2. The student should acquire four credits through MOOCs compulsory to award the Honour Degree.

S.No.	Course Code	Course Title	Contact Hours per week		Credits	
			L	Т	Р	
1	22A03H01	Fracture Mechanics	3	1	0	4
2	22A03H02	Computational Fluid Dynamics	3	1	0	4
3	22A03H03	Analysis and Synthesis of Mechanisms	3	1	0	4
4	22A03H04	Applications of Optimization Techniques	3	1	0	4
5	22A03H05	MOOC				4

LIST OF MINOR COURSES OFFERED BY MECHANICAL ENGINEERING

S.No.	Course code	Minor Title Hours per		er we	eek	Credits
1.	22A03M01	Modern Manufacturing Methods	3	1	0	4
2.	22A03M02	Engineering Thermodynamics	3	1	0	4
3.	22A03M03	Material Science & Engineering	3	0	2	4
4.	22A03M04	Design of Machine Elements	3	1	0	4
5.	22A03M05	Additive Manufacturing	3	0	2	4
6.	22A03M06	Synthesis and characterization of Composites	3	1	0	4
7.	22A03M07	Mechatronics & MEMS	3	1	0	4
8.	22A03M08	Hybrid Vehicles	3	1	0	4



Design of Heat Transfer Equipment							
Course Code	L:T:P:S	Credits	Exam Marks	Exam Dura	tion	Course Type	
22A0332Ta	3: 0:0:0	3	CIE: 30 SEE:70	3Hours	5	PEC	
Course Objectiv	ves:		•				
To introdu	ce basic meth	ods of desig	gn of heat exchange	ers.			
To familia	rize with the	design proce	edures of various he	eat transfer e	quipm	ient	
Syllabus					Tota	l Hours:42	
UNIT - I		Inti	roduction			12 Hrs	
Methods of de	sign of Hea	t Exchange	ers Concept of I	Logarithmic	Mear	1 Temperature	
Difference: Exp	ression for	single pass	parallel-flow and	l single-pass	cour	nter flow heat	
exchangers – De	rivation from	n first princi	ples, Special Cases	s, LMTD for	a sin	gle-pass cross-	
flow heat exchange	anger , Nun	nerical Pro	blems, Arithmetic	Mean Tem	perati	ure Difference	
[AMTD], Relati	on between	AMTD an	d LMTD, Logical	l Contrast b	etwee	n AMTD and	
LMTD, LMTD	of a single-p	ass heat ex	changer with linea	arly varying	overa	ll heat transfer	
coefficient [U] al	long the lengt	h of the hea	t exchanger, Nume	rical problen	ıs.		
Concept of Effe	ectiveness: Ei	ffectiveness	-Number of Transf	er Units App	oroach	, Effectiveness	
of single-pass pa	rallel-flow ar	nd counter-f	low heat exchange	rs, Physical s	signifi	cance of NTU,	
Heat capacity rat	tio, Different	special case	es of the above app	proach, Chart	t solut	ions pertaining	
to Effectiveness-	NTU approad	h, Numeric	al problems				
UNIT - II	Design	of Shell and	d Tube Heat Exch	angers		10 Hrs	
Single-Pass, One	shell-Two tuł	be [1S-2T] a	ind other heat exchange	angers, Indus	strial v	versions of the	
same, Classificat	tion and No	menclature,	, Baffle arrangen	nent, Types	of I	Baffles, Tube	
arrangement, Typ	es of tube p	itch lay-out	s, Shell and Tube	side film co	oeffici	ents, Pressure	
drop calculations,	Numerical pi	oblems on l	Design of Shell and	l Tube Heat I	Excha	ngers	
UNIT - III	Desi	gn of Hair-	Pin Heat Exchang	gers		10 Hrs	
Introduction to Co the same, Film co of hair-pin heat exchangers, Com standards, Numeri	ounter-flow E efficients in t exchangers, prehensive 1 ical problems	Oouble-pipe tubes and an Series and Design Alg on Design (or Hair-Pin heat ex muli, Pressure drop d Series-Parallel sorithm for hair-p of Hair-Pin Heat Ex	cchangers, In b, Augmentat arrangements in heat exc cchangers.	dustri tion of s of hange	al versions of performance hair-pin heat rs, Industrial	
UNIT - IV	De	esign of Plat	te Heat Exchanger	rs		12 Hrs	
Introduction, Mec performance limi calculations, Num	chanical Featu its, Passes a erical proble	ares – Plate and flow a ns on Desig	pack and the fram arrangements, Hea on of Plate Heat Exc	ne, Plate type at transfer a changers.	es, Ac and p	lvantages and pressure drop	

UNIT	C-V Design of Boilers, Condensers and Cooling Towers	12 Hrs
Boiling	g: types of boiling, various empirical relations pertaining to boiling,	Numerical
problem	ns.	
Conde	nsation – Types of condensers, Nusselt's theory on laminar film-wi	se condensation,
Empiri	cal Refinements, Several empirical formulae, Numerical problems.	
Coolin	g Towers: basic principle of evaporative cooling, classification of o	cooling towers,
empirio	cal relations pertaining evaporative cooling. Numerical problems on	Design of Boilers,
Conder	nsers and Cooling Towers	
Course	e Outcomes (CO):	
Upon s	successful completion of the course, the students will be able to	
•	Apply LMTD and NTU methods for the design of heat exchangers	
•	Design shell and tube heat exchangers used in process industries.	
•	Design hair-pin heat exchangers used in process industries.	
•	Design plate heat exchangers used in milk industries.	
•	Design boilers, condensers and cooling towers used in steam powe	r plants.
Textbo	ooks:	
1.	Compact Heat Exchangers, Kays, W. M. and London, A. L., McGr	aw – Hill,
	New York, 2nd Edition, 1998.	
2.	Fundamentals of Heat Exchanger Design, Shah, R. K. and Sekulic	, D. P.,
	John Wiley and Sons, New Jersey, 2003.	
Refere	nce Books:	
1.	Fundamentals of Heat and Mass Transfer, Incropera, F. P. and Dew	vitt, D. P., 7th
	Edition, John Wiley and Sons, New York, 2013.	
Z .	Kern, Donald O. Process heat transfer. No. 04: OC320, K4, 1950.	



		r	Fribology		
Course Code	L:T:P:S	Credits	Exam Marks	Exam Durati	ion Course Type
22A0332Tb	3: 0:0:0	3	CIE: 30 SEE:70	3Hours	PEC
Course Objectiv	ves:	•	•		
To familia	rize with the	selection of	lubricating system	for different m	nachine
componen	its.				
To impart	knowledge of	n design of l	pearings for a giver	n application	
Syllabus				ſ	Fotal Hours:42
UNIT - I					12 Hrs
Basic Concepts:	Oil Viscosity	and tempera	ature and pressure of	effect on viscos	sity of lubricants,
viscosity index, d	etermination of	of viscosity,	viscosity measurer	ments, friction	and wear
mechanisms- met	hods of fluid	film formati	on.		
Lubrication: clas	sification of l	lubricant oil	s, characteristics of	liquid, grease	and solid,
lubricants- additiv	/es.				
Bearing Materia	ls: Classificat	tion of bearing	ng materials-desira	ble properties,	advantages and
applications					
UNIT - II					10 Hrs
Hydrostatic Be	arings: Intro	oduction to	hydrostatic lubr	rication-Viscou	is Flow through
Rectangular Slot	, Hydrostatic	Bearing A	analysis -Flat Circ	ular pad, Fla	t square pad and
Conical thrust Be	aring - Energy	y losses and	Optimum design a	nd Temperatur	e rise.
UNIT - III					10 Hrs
Hydrodynamic	bearings: Pr	inciples of	hydrodynamic lub	prication-mech	anism of pressure
development in tl	he oil-film, po	etroffs equa	tion-Reynolds's eq	uation for two	-dimensional flow;
hydrodynamic jou	urnal bearings	-Analysis of	f infinitely long and	d infinitely sho	ort bearings- Effects
of side leakage, I	Friction in slie	ding bearing	g heat generated an	d heat dissipa	ted. Hydrodynamic
thrust bearings- A	nalysis of pla	ne slider be	aring with fixed Pa	d	
UNIT - IV					12 Hrs
Analysis of Hyd	lrostatic Squ	ieeze-film I	Lubrication: Circu	ılar plate appı	roaching a plane -
rectangular plate	approaching a	a plane and a	pplications of sque	eze-film Lubri	ication
Aerostatic Bear	ring lubrica	tion : Intro	duction, merits	and demerits	s, applications to
hydrodynamic an	d hydrostatic	thrust bearir	ngs, externally pres	ssurized gas be	earings.
Dry rubbing Be	arings: porot	us metal be	arings and oscillat	ory journal be	earings –qualitative
approach only.					
UNIT - V					12 Hrs
Oil Seals &Gask	ets: Different	type of med	chanical seals-static	and dynamic,	essential
properties of the s	seals- oil fling	er rings and	oil grooves.		
Failure of Tribol	logical Comp	onents: Fai	lure analysis of pla	in bearings, rol	lling bearings,

gears, seals-characteristics and causes

Upon successful completion of the course, the students will be able to

- Select the appropriate lubricant and material for specific application design and analyze the hydrostatic and hydrodynamic lubrication systems used in bearings.
- Analyze and explain the hydrostatic squeeze-film lubrication, aerostatic lubrication systems used in bearings and dry rubbing bearing.
- Illustrate different types of seals and gaskets used in mechanical systems and describe the behavior of tribological components subjected to different working conditions.

Textbooks:

- 1. Gwidon Stachowiak and Andrew W Batchelor, Engineering Tribology,
- 2. Butterworth-Heinemann, 4th Edition, 2013
- V. B. Bhandari, Design of Machine Elements, McGraw-Hill Education 4th Edition, 2013.

- 1. H.G. Phakatkar& R.R. Ghorpade, Tribology, Nirali Prakashan.,4th Edition, 2012
- 2. Er. Sushil Kumar Srivastava, Tribology in Industries, S.Chand& Company Ltd, 2nd Edition, 2011
- 3. M.J. Neale, Tribology Handbook, Butterworth, 2nd Edition, 2001



Unconventional Machining Processes								
Course Code	L:T:P:S	Credits	Exam Marks	Exam Dura	tion	Course Type		
22A0332Tc	3: 0:0:0	3	CIE: 30 SEE:70	3Hours	5	PEC		
Course Objecti	ves:				·			
Define	e various Mod	ern Machini	ing Processes.					
 Acqui 	re knowledge	in the eleme	entary mechanism a	and machinal	oility o	f materials		
with d	ifferent Mode	ern Machinir	ng Processes.					
• Deterr	nine basic prin	nciples of op	peration for each pr	ocess and the	eir app	lications.		
• State	various param	eters influen	icing MRR in Non	– Traditional	Mach	ining Process.		
Classi	fy and underst	tand the wor	king of Additive N	lanufacturing	g Proce	esses.		
Syllabus					Total	Hours:42		
UNIT - I	Non –	- Traditiona	ll Machining Proc	esses		12 Hrs		
Introduction, Nee	d, Classificati	on and Brie	f Overview, Consid	lerations in F	rocess	selection,		
Materials, Applic	ations.							
Mechanical Ene	ergy Based I	Processes:	Abrasive Jet Macl	nining, Wate	er Jet	Machining,		
Abrasive Water J	et Machining	, Ultra Soni	c Machining – Wo	rking Princip	ole, De	scription of		
Equipment, Proc	ess Paramete	ers, Metal	Removal Rate, A	pplications,	Adva	ntages and		
Limitations.								
UNIT - II	Ele	ectrical Ene	rgy Based Process	es		10 Hrs		
Electric Discharg	ge Machining	g – Workin	g Principles, Desc	cription of I	Equipn	nent, Process		
Parameters, Surfa	ace Finish an	d MRR, El	ectrode / Tool, Po	wer and Co	ntrol (Circuits, Tool		
Wear, Dielectric	Fluid, Flushin	ig, Advantag	ges, Limitations and	d Application	ns. Wii	re cut EDM –		
Working Principl	e and Applica	tions.						
UNIT - III	Chemica	l and Electr	o Chemical Energ	gy Based		10 Hrs		
		P1	rocesses					
Chemical Machin	ning and Elec	tro Chemica	al Machining – We	orking Princi	iple, D	Description of		
Equipment, Etch	ants, Maskan	ts, Techniq	ues of Applying	Maskants, P	rocess	Parameters,		
Surface Finish	and MRR,	Electro C	hemical Grinding	, Electro	Chemi	cal Honing,		
Applications, Adv	vantages and l	Limitations						
UNIT - IV	Th	ermal Ener	gy Based Processe	es:		12 Hrs		
Laser Beam Mac	chining and D	Drilling, Plas	sma Arc Machinin	g. Electron	Beam	Machining –		
Working Principl	e, Description	n of Equipm	ent, Process Param	eters, Applic	ations	, Advantages		
and Limitations.	, I	1 1	,	, 11		ý U		
UNIT - V		Additive	Manufacturing			12 Hrs		
Introduction to A	dditive Manuf	facturing, Cl	assification of Add	litive Manufa	cturing	g Processes,		
Working Principl	e, Advantages	s, Limitation	s and Applications	of Sterolitho	graphy	y (SLA),		
Fused Deposition Modeling, Selective Laser Sintering, Laminated Object Manufacturing								

At the end of the course, the student will be able to

- Illustrate advanced machining processes, cutting tools and cutting fluids for a specific material and part features.
- Classify the mechanism of Mechanical Energy based machining processes, its applications and limitations.
- Differentiate Electrical Energy Based machining processes, mechanism of metal removal, machine tool selection.
- Interpret Electro Chemical machining process, economic aspects of ECM and problems on estimation of metal removal rate.

Textbooks:

- 1. Jain V.K., Advanced Machining Processes, 1st Edition, Allied Publishers Pvt. Ltd., New Delhi, 2007.
- 2. Pandey P.C and Shan H.S., Modern Machining Processes, 1/e, McGraw Hill, New Delhi, 2007.
- 3. Ian Gibson, David W. Rosen, Brent Stucker, Additive Manufacturing Technologies: Rapid Prototyping to Direct Digital Manufacturing, 1/e, Springer, 2010.

- 1. Chua C.K., Leong K.F. and Lim C.S., Rapid Prototyping: Principles and Applications, 2/e, World Scientific Publishers, 2003.
- 2. Benedict G.F., Nontraditional Manufacturing Processes, 1/e, CRC Press, 1987.
- 3. Mishra P.K., Nonconventional Manufacturing, 1/e, Narosa Publishing House, New Delhi, 2014.
- 4. McGeough J.A., Advanced Methods of Machining, 1/e, Springer, 1988.



Refrigeration and Air Conditioning							
Course Code	L:T:P:S	Credits	Exam Marks	Exam Duratio	n Course Type		
22A0333Ta	3: 0:0:0	3	CIE: 30 SEE:70	3Hours	PEC		
Course Objectiv	es:		·				
To introdu	uce the basic c	cycles of var	ious refrigeration s	ystems, their pe	rformance		
evaluation	along with d	etails of syst	tem components an	d refrigerants u	sed.		
To impart	knowledge or	n psychrome	etric properties and	processes and c	lesign of air-		
conditionir	ng systems						
Syllabus				T	otal Hours:42		
UNIT - I					12 Hrs		
Introduction: No	eed and Appli	cations of re	frigeration, Unit of	refrigeration ar	nd C.O.P,		
Methods of refrig	eration.						
Aircraft Refrige	ration: Refrig	geration need	ds of Aircrafts - Air	craft refrigerat	ion systems -		
working and their	analysis.						
Thermoelectric 1	Refrigeration	: Working p	principle and applic	ations.			
UNIT - II			1 11		10 Hrs		
Vapor Compress	sion Refriger	ation: Work	king principle and e	ssential compo	nents of the plant,		
actual cycle, effect	ct of sub-cooli	ing, super-he	eating, evaporator a	and condenser p	ressures on		
system performar	nce – use of p-	h charts.		Ĩ			
Refrigerants: I	Desirable pro	operties, cl	assification, Nom	enclature, app	lication, Ozone		
Depletion, Globa	l Warming.	-					
UNIT - III					10 Hrs		
VCR System Co	⊥ mponents: C	lassification	and working of Co	mpressors. Cor	densers.		
Evaporators and I	Expansion dev	vices.					
		·	1 1' CATT	2			
Vapor Absorptio	on System: D	$\frac{1}{2}$	nd working of NH	3 - water system	m,Calculation of		
maximum COP	and Descrip	d a hand w	vorking of Li Br	-water (1wo	shell) System,		
LINIT IV		u absorbent.			12 II.wa		
UNII - IV	P- Davahuan	notuio Duo	Angener Deviewy	of Davahaama	12 Hrs		
Psychrometry Developmetric D	a Psychron	netric Pro	ing sonsible coo	ling humidifi	artic Properties,		
hymidification	oling and do	humidificat	ing, sensible coo	diabatia humid	fightion hosting		
and humidification	n adjabatio m	-numumcal	a air streams	ulabalie liulillu	incation, neating		
			o all sucallis.				
UNIT - V					12 Hrs		
Design of Air-Co	onditioning S	ystems: Cha	aracterization of Se	nsible and laten	t heat loads, Need		
tor Ventilation, C	onsideration of	ot Infiltratio	n, Load concepts o	t RSHF, GSHF	Problems,		
Concept of ESHF	Concept of ESHF and ADP. Comfort Air conditioning - summer air conditioning, winter air						

conditioning, Air conditioning Load Calculations.

Upon successful completion of the course, the students will be able to

- Analyze different kinds of aircrafts refrigeration systems and illustrate the working of thermoelectric refrigerator.
- Analyze single stage vapor compression refrigeration systems and select a suitable refrigerant for a given application.
- Classify VCR system components and illustrate the working of various types of vapour absorption refrigeration systems.
- Estimate the psychrometric properties and analyze various psychrometric processes.
- Estimate the cooling/heating loads on the air-conditioning equipment for a given application

Textbooks:

- 1. C P Arora, "Refrigeration and Air Conditioning", Tata McGraw-Hill Education, 3rd edition.
- 2. S C Arora & Domkundwar, "A Course in Refrigeration and Air conditioning", Dhanpat Rai publications, 5th edition.
- 3. 3. Manohar Prasad, "Refrigeration and Air Conditioning", New Age publications, Revised 2nd edition.

- 1. Dossat, "Principles of Refrigeration", Pearson Education.
- **2.** Anantha Narayanan, "Basic Refrigeration and Air-Conditioning", Tata McGraw-Hill Education, 4th edition.



Introduction to Robotics							
Course Code	Course Code L:T:P:S Credits Exam Marks Exam Duration Course T						
22A0333Tb	3: 0:0:0	3	CIE: 30 SEE:70	3Hours	PEC		
Course Ob	jectives:				·		
• The objec	tives of this co	ourse are Ide	entify robots and its	s peripherals f	for satisfactory		
operation	and control of	f robots for i	ndustrial and non-i	ndustrial appl	lications.		
Syllabus Total Hours:42							
UNIT - I		Rok	oot Basics		12 Hrs		
Automation an	d Robotics:	Robot-Bas	ic concepts, Nee	d, Law, Hi	story, Anatomy,		
specifications. R	obot configur	ations-cartes	sian, cylinder, pol	ar and articu	late. Robot wrist		
mechanism, Prec	ision, accuracy	y, repeatabil	ity, work and volu	ne of robot.			
UNIT - II		Robo	t Elements		10 Hrs		
End effectors-C	lassification-	Types of N	Aechanical actuation	on, Gripper d	esign, Robot drive		
system Types, Po	osition and ve	locity feedb	ack devices-Robot	joints and li	nks-Types, Motior		
interpolation							
UNIT - III	R	obot Kinen	natics And Contro	1	10 Hrs		
manipulators – Pe	oint to point, C	Continuous I	Path Control, Robo	t programmin	<u>g</u> 12 Hrs		
UNII - IV		KOD	ot Sensors		12 HIS		
Sensors in robo sensor-Light sen Intelligence.	ot – Touch se sors, Pressur	ensors-Tacti e sensors,	le sensor – Proxi Introduction to M	mity and ran Machine Visi	nge sensors. Force ion and Artificial		
UNIT - V		Robot	Applications		12 Hrs		
Industrial applic	cations of rob	ots-Medical	, Household, Enter	tainment, Spa	ice, Underwater,		
Defense, Disaster	management	. Application	ns, Micro and Nano	probots, Futur	e Applications.		
Course Outcom	es (CO):						
On completion of	f the course the	e student wi	ll be able to:				
• List and e	xplain the bas	ic elements	of industrial robots				
• Analyse r	obot kinemati	cs and its co	ntrol methods.				
Classify t	he various sen	sors used in	robots for better po	erformance.			
Summariz	ze various indu	ustrial and n	on-industrial applic	ations of rob	ots		
Toythoolyge							
1 Mikell P	Groover Mite	hell Weiss	Roger N Nagel Ni	cholas G Odr	ev "Industrial		
Robotics '	Technology		itoger in mager, m		cy, maastrar		
2. Programn	ning and Appl	ications". Ta	ata –McGraw Hill I	Pub. Co., 200	8.		
3. Deb.S.R a	and Sankha De	eb, "Robotic	s Technology and I	Flexible Auto	mation", Tata		
McGraw	Hill Publishing	g Company	Limited, 2010.				

- 1. Klafter.R.D, Chmielewski.T.A, and Noggin's., "Robot Engineering: An Integrated Approach", Prentice Hall of India Pvt. Ltd., 1994.
- Fu.K.S, Gonzalez.R.C&Lee.C.S.G, "Robotics control, sensing, vision and intelligence", Tata- McGraw Hill Pub. Co., 2008
- 3. Yu. "Industrial Robotics", MIR Publishers Moscow, 1985

RG 22 Regulations



Finite Element Method							
Course Code	L:T:P:S	Credits	Exam Marks	Exam Duratio	n Course Type		
22A0333Tc	3: 0:0:0	3	CIE: 30 SEE:70	3Hours	PEC		
Course Obje	ctives:						
To familia	rize with the	concepts of	finite element meth	od for structura	l, thermal and		
dynamic a	nalysis						
Syllabus				То	otal Hours:42		
UNIT - I					12 Hrs		
Introduction: stres	s and equilib	rium, strain	– displacement rela	tions, stress – s	train relations,		
variational and we	eighted residu	al methods.					
Finite Element M	ethod: Introdu	uction to fini	ite element method	s, steps in finite	element method		
applications, adva	ntages and di	sadvantages	of finite element n	nethod.			
One Dimensional	Bar Problem	ns: 1-D bar	element - shape fu	nctions – stiffn	ess matrix and		
load vector- asse	embly of mat	trices – trea	tment of boundar	v conditions-Or	ne dimensional		
quadratic element							
UNIT - II					10 Hrs		
Analysis of Trus	ses: Local a	nd global co	ordinate systems,	transformation	matrix, element		
stiffness matrix ,	determinatio	on of displa	cements and stres	ses Analysis o	f Beams: Beam		
element - shape	functions ar	nd element	stiffness matrix,	load vector,	determination of		
deflections, supp	ort reactions						
UNIT - III					10 Hrs		
Two Dimensiona	l Problems:	Plane stress	and plane strain pro	oblems , constar	nt strain		
triangle(CST) eler	ment – shape	functions, J	acobian of transfor	mation, strain d	isplacement		
matrix , element s	tiffness matri	x , determin	ation of deflections	and stresses.			
Isonarametric F	ormulations	· Coordinat	e transformation	sub iso and s	uper parametric		
elements, iso pa	rametric for	nulations o	f bar element, qu	adrilateral eler	nent, numerical		
integration – Gaus	ssian quadrati	re approach	l.	***************************************			
UNIT - IV					12 Hrs		
Steady State Hea	it Transfer A	nalvsis: 1-	D steady state therr	nal analysis of r	plane and		
composite walls, a	analysis of a f	ĩn.	j 				
UNIT - V					17 Hrs		
Dynamic Analyci	is: Free longi	tudinal and t	manaziona zibratian	a aigan yaluga	1		
			ransverse viniariou	N EIVEILVAILLEN	and		

Upon successful completion of the course, the students will be able to

- Apply variational and weighted residual methods to solve differential equations.
- Determine the stresses and strains in one dimensional bar problems.
- Analyze trusses and beams to determine the stresses induced.
- Determine the displacements and stresses in 2d problems.
- Develop iso parametric formulations for finite elements and solve them using Numerical techniques.
- Analyze 1-d heat transfer problems to determine rate of heat transfer and Temperature distribution.
- Determine natural frequencies of vibrating systems using finite element method.

Textbooks:

- 1. Chandragupta, Ashok and Belaunde, "Introduction to Finite Elements in Engineering ", Prentice Hall,2011
- Daryl L Logan, "A first course in finite element method", Cengage Learning. 2011.

- 1. Robert D Cook, "Finite element modeling for stress analysis ", John wily & Sons.
- SS Rao, "The Finite Element Methods in Engineering", Elsevier Science, 5th Edition, 2011.
- JN Reddy, "An introduction to Finite Element Method", McGraw Hill Education, 2006.
- 4. S.S. Bhavikatti," Finite Element Analysis", New Age International Pvt Ltd , 2015.



		Power F	Plant Engineering				
Course Code	L: T:P:S	Credits	Exam Marks	Exam Dura	ntion	Course Type	
22A0334Ta	3: 0:0:0	3: 0:0:0 3 CIE: 30 SEE:70 3Hours PEC					
Course Objecti	ves:						
To introdu	ace the working	ng of various	s power plants.				
To familia	arize with pow	ver plant eff	luents and power pl	ant economi	cs.		
Syllabus					Tota	l Hours:42	
UNIT - I	Intro	oduction to	the Sources of En	ergy		12 Hrs	
Resources and De	evelopment of	f Power in Ir	ndia. Steam Power	Plant: Plant	Layo	out,	
Components, Wo	rking of diffe	rent Circuits	3.				
Coal Handling S	ystems: Type	es of fuels, C	Coal handling, Choi	ce of coal ha	ndlin	g equipment	
UNIT - II		Combu	stion Process			10 Hrs	
Methods of Coal	firing, Overfe	ed and Unde	erfeed stoker firing	- Principles	and ty	pes of stoker	
firing systems, Pı	ulverized fuel	firing - Prin	ciple, Types of bur	ners and Mill	ls, Flı	uidized Bed	
Combustion, Cyc	lone Burner.						
Ash and Dust ha	ndling: Type	s of Ash har	ndling systems, Wo	rking princip	oles of	f various Dust	
collectors.							
Cooling towers:	Types of Coo	ling towers	and their working.				
UNIT - III		Cog	generation			10 Hrs	
Working principl	es, Combined	stem and ga	as turbine plants, Co	ombined gas	and c	liesel power	
plants, limitations	5.						
Hydroelectric Po	ower Plant: V	Vater power	, Hydrological cycl	e, Hydrograp	ohs, F	low duration	
curve, Mass curve	e. Hydroelecti	ric Power pl	ant layout with aux	iliaries, class	sificat	ion of dams,	
spill ways and su	rge tanks.						
UNIT - IV		Nuclear	r Power Plant			12 Hrs	
Nuclear fusion and fission, working of nuclear plant, Components of Nuclear Reactor, Classification of reactors, Pressurized water reactor, Boiling water reactor, Gas cooled reactor, CANDU reactor, Fast breeder reactor, Nuclear waste and its disposal.							
UNIT - V	Environ	mental Asp	ects of Power Gen	eration		12 Hrs	
Effluents from po	wer plants an	d their impa	ct on environment,	Pollutants an	nd Po	llution	
standards, Metho	ds of Pollution	n control.					
Load Calculation	ns: Load curv	es, load dur	ation curve, definiti	ions of conne	ected	load, maximum	
demand, demand	factor, averag	ge load, load	factor, diversity fa	ctor – related	l exer	cises.	

Upon successful completion of the course, the students will be able to

- Illustrate working of different circuits, and coal handling systems of steam Power plant.
- Describe the methods of coal firing, ash handling systems and cooling towers in steam power plant.
- Understand the working of hydraulic and combined operations of power plants .
- Explain the working of nuclear power plant.
- Familiarize with the power plant effluents, economics and their control.

Textbooks:

- 1. G.D. Rai, "An Introduction to Power Plant Technology", Khanna Publishers, 2006, 5th Edition.
- P.K.Nag, "Power Plant Engineering", Tata McGraw-Hill Education, 2008, 3rd Edition

- 1. S.C. Arora and S. Domkundwar "A Course in Power Plant Engineering",
- 2. Dhanpat Rai & Co. (P) Limited, 2004, 5th edition.
- 3. R. K. Rajput, "A Text Book of Power Plant Engineering", Laxmi Publications(p) Ltd. 2009, 4th Edition.
- 4. M.M.El-Wakil, "Power Plant Technology", Tata McGraw-Hill Education, Revised 2nd edition.
- 5. R.K Hedge "Power plant Engineering "Pearson India Education service Limited, 2016, 2nd edition.



		Non-Dest	ructive Evaluation	1		
Course Code	L:T:P:S	Credits	Exam Marks	Exam Dura	tion	Course Type
22A0334Tb	3: 0:0:0	3	CIE: 30 SEE:70	3Hours	5	PEC
Course Objecti	ves:					
To familia	arize with the	concepts of	various NDT techn	iques to iden	tify tl	he defect in a
mechanic	al component					
Syllabus					Tota	l Hours:42
UNIT - I	Introdu	ction to ND	T and Radiograp	hy Test		12 Hrs
Introduction: C	Overview of n	on-destructiv	ve testing, types of	materials tes	ting, I	Preliminary
NDT methods, N	NDT methods					
Radiography te	st: Sources o	f X ravs an	d Gamma Ravs. t	neir propertie	es and	d interaction
with matter, radi	ographic test.	, film chara	cteristics, radiogra	phic equipm	ent, F	Radiographic
techniques, safet	y aspects, ad	vantages, li	mitations, industria	application	ns of	radiography
test.		U ,	,	11		017
UNIT - II		Ultra	asonic Test			10 Hrs
Principle of wav	e propagation	, piezo-elec	tric effect, ultrason	nic transduce	ers - o	characteristics,
ultrasonic equipr	nent, testing	procedure,	interpretation, eva	luation, adva	antage	es, limitations,
industrial applica	tions of ultras	onic testing				
UNIT - III		Liquid l	Penetrant Test			10 Hrs
Basic concepts	liquid nenetra	ant system	surface preparatio	n test proce	edure	examination
interpretation ev	aluation adv	antages lim	itations industrial	applications	of lic	uid penetrant
testing.	uruuron, uu v	antages, min	nutrons, muustinui	apprications	01 110	Juiu penetrunt
UNIT - IV		Magneti	c Particle Test			12 Hrs
	1			- 4 :	4 4 -	
Magnetic materia	ils, principle (of magnetic	particle test, magn	etic particle	test e	quipment, test
procedure, interp	relation and e	valuation, ad	ivantages, limitatio	ns, industria	i appi	ications of the
Inagnetic particle		Eddy	Current Test			13 II.uc
UNII - V Drin sin 1s of odds		Eady	dda annata ina			12 Hrs
Principle of eddy current, factors affecting eddy currents, impedance diagram, eddy current test						
system, test cons,	, advantages, I	innitations a	na maustriar appir	cations of ed	ay cu	frent test.
Course Outcom	es (CO):					
Upon successful	completion o	of the course	e, the students will	be able to		
• Descri	ibe choose a s	uitable non-	destructive method	to find the d	efect	in the given
mecha	nical compon	ents using r	adiography test, ult	rasonic test,	liquid	penetrant test,
magnetic particle test and eddy current test						

Textbooks:

- 1. J Prasad and GCK Nair, "Non-Destructive Test and Evaluation of Materials", Tata McGraw-Hill Education, 2nd edition, 2011.
- 2. B Raj, T Jayakumar and M Thavasimuthu, "Practical Non Destructive Testing",
- 3. Alpha Science International Limited, 3rd edition, 2017.

- 1. V Jayakumar and K Elangovan, "Non-Destructive Testing of Materials", Lakshmi Publications, 2nd edition, 2018.
- 2. George V. Crowe, "An Introduction to Nondestructive Testing", American Society for Nondestructive Testing, 3rd edition, 2009.
- 3. Ravi Prakash, "Non-Destructive Testing Techniques", New age international publishers, 1st edition, 2021.



	F	undamenta	ls of drone techno	logy				
Course Code	L:T:P:S	Credits	Exam Marks	Exam Dura	tion	Course Type		
22A0334Tc	3: 0:0:0	3	CIE: 30 SEE:70	3Hours		PEC		
Course Objecti	ves:		•					
The course should	d enable the st	tudents to:						
To ma	• To make the students to understand the basic concepts of UAV drone systems.							
To int	• To introduce the stability and control of an aircraft							
Syllabus					Tota	l Hours:42		
UNIT - I		Introduc	ction to Drones			12 Hrs		
Introduction to	Unmanned A	ircraft Syste	ems, History of U	JAV drones,	clas	sification of		
drones, System C	omposition, a	pplications						
UNIT - II	I	Design of UA	AV Drone Systems	5		10 Hrs		
Introduction to	Design and	Selection	of the System,	Aerodynam	ics a	and Airframe		
Configurations, C	Characteristics	of Aircraft	Types, Design Sta	ndards and H	Regul	atory Aspects-		
India Specific, De	esign for Steal	lth.						
UNIT - III	UNIT - IIIAvionics Hardware of Drones10 Hrs							
Autopilot, AGL- processor, integra	Autopilot, AGL-pressure sensors servos-accelerometer –gyros-actuators- power supply- processor, integration, installation, configuration.							
UNIT - IV	Comm	nunication,	Payloads and Cor	ntrols		12 Hrs		
Communication,	Payloads ar	nd Controls	: Payloads, Teler	metry, Tracl	king,	controls-PID		
feedback, radio c	control freque	ncy range, 1	nodems, memory s	system, simu	lation	n, ground test-		
analysis-trouble s	hooting							
UNIT - V		Navigati	on and Testing			12 Hrs		
Navigation and T	esting: Waype	oints naviga	tion, ground contro	l software, S	ystem	n Ground		
Testing, System I	n-flight Testi	ng, Future P	rospects and Challe	enges				
Course Outcome	es (CO):							
The student show	uld able to:							
Ability to design UAV drone system								
• To un	derstand work	ing of differ	rent types of engine	es and its area	ı of ap	oplications.		
• To un	derstand static	and dynam	ic stability dynami	c instability a	and co	ontrol concepts		
To kn	ow the loads t	aken by airc	eraft and type of con	nstruction and	d also	construction		
materi	als used in D	rones						

Textbooks:

- 1. Reg Austin "Unmanned Aircraft Systems UAV design, development and deployment", Wiley, 2010.
- 2. Robert C. Nelson, Flight Stability and Automatic Control, McGraw-Hill, Inc, 1998.
- 3. Kimon P. Valavanis, "Advances in Unmanned Aerial Vehicles: State of the Art and the Road to Autonomy", Springer, 2007

- 1. Paul G Fahlstrom, Thomas J Gleason, "Introduction to UAV Systems", UAV Systems, Inc, 1998.
- **2.** Dr. Armand J. Chaput, "Design of Unmanned Air Vehicle Systems", Lockheed Martin Aeronautics.



		Disast	er Management			
Course Code	L:T:P:S	Credits	Exam Marks	Exam Dura	tion	Course Type
22A0151T	3: 0:0:0	3	CIE: 30 SEE:70	3Hours		OEC
Course Objecti	ves:					
The course shoul	d enable the st	tudents to:				
To ma	the studen	ts to underst	and the basic conce	epts of UAV c	drone	systems.
To int	roduce the sta	bility and co	ontrol of an aircraft			
Syllabus					Total	Hours:42
UNIT - I		Introduc	ction to Drones			12 Hrs
Introduction to	Unmanned A	ircraft Syste	ems, History of U	JAV drones,	class	sification of
drones, System C	omposition, a	pplications				
UNIT - II	Ι	Design of U A	AV Drone Systems	5		10 Hrs
Introduction to	Design and	Selection	of the System,	Aerodynami	ics a	and Airframe
Configurations, C	Characteristics	of Aircraft	Types, Design Sta	ndards and R	legula	atory Aspects-
India Specific, D	India Specific, Design for Stealth.					
UNIT - III	UNIT - IIIAvionics Hardware of Drones10 Hrs					
processor, integra	tion, installat	ion, configu	ration.	gyros-actuator	s- pc	ower supply-
UNIT - IV	Comr	nunication,	Payloads and Cor	ntrols		12 Hrs
Communication,	Payloads an	nd Controls	s: Payloads, Teler	metry, Track	king,	controls-PID
feedback, radio c	control freque	ncy range, 1	modems, memory s	system, simul	lation,	, ground test-
analysis-trouble s	hooting					
UNIT - V		Navigati	on and Testing			12 Hrs
Navigation and T	esting: Wayp	oints naviga	tion, ground contro	l software, Sy	ystem	Ground
Testing, System I	n-flight Testi	ng, Future P	rospects and Challe	enges		
Course Outcom	es (CO):					
The student sho	uld able to:					
Ability to design UAV drone system						
• To un	derstand work	ing of differ	rent types of engine	es and its area	of ap	plications.
• To un	derstand static	and dynam	ic stability dynami	c instability a	nd con	ntrol concepts
To kn	ow the loads t	aken by airc	craft and type of con	nstruction and	l also	construction
mater	ials used in D	rones				

Textbooks:

- 1. Reg Austin "Unmanned Aircraft Systems UAV design, development and deployment", Wiley, 2010.
- 2. Robert C. Nelson, Flight Stability and Automatic Control, McGraw-Hill, Inc, 1998.
- 3. Kimon P. Valavanis, "Advances in Unmanned Aerial Vehicles: State of the Art and the Road to Autonomy", Springer, 2007

- 1. Paul G Fahlstrom, Thomas J Gleason, "Introduction to UAV Systems", UAV Systems, Inc, 1998.
- **2.** Dr. Armand J. Chaput, "Design of Unmanned Air Vehicle Systems", Lockheed Martin Aeronautics.



(Common to all Except EEE) Course Code L:T:P:S Credits Exam Marks Exam Duration Course Type 22A0241Ta 3: 0:0:0 3 CIE: 30 SEE:70 3Hours OEC Course Objectives: The course should enable the students to: Overview of the technologies required for the smart grid Switching techniques and different means for data communication	e					
Course CodeL:T:P:SCreditsExam MarksExam DurationCourse Typ22A0241Ta3: 0:0:03CIE: 30 SEE:703HoursOECCourse Objectives:The course should enable the students to:• Overview of the technologies required for the smart gridSwitching techniques and different means for data communication	e					
22A0241Ta 3: 0:0:0 3 CIE: 30 SEE:70 3Hours OEC Course Objectives: The course should enable the students to: Overview of the technologies required for the smart grid Switching technologies and different means for data communication						
Course Objectives: The course should enable the students to: • Overview of the technologies required for the smart grid • Switching techniques and different means for data communication						
 The course should enable the students to: Overview of the technologies required for the smart grid Switching techniques and different means for data communication 						
 Overview of the technologies required for the smart grid Switching techniques and different means for data communication 						
 Switching techniques and different macro for data communication 						
• Switching techniques and different means for data communication						
• Standards for information exchange and smart metering						
 Methods used for information security on smart grid 						
Smart metering and protocols for smart metering						
Power quality management with upgraded technologies.						
Syllabus Total Hours: 48						
Unit-I Introduction to Smart Grid 10 Hrs						
Evolution of Electric Grid. Concept. Definitions and Need for Smart Grid. Smart grid drive	rs.					
functions, opportunities, challenges and benefits, Difference between conventional & Sm	art					
Grid, Concept of Resilient & Self-Healing Grid, Present development & International polic	ies					
in Smart Grid, Diverse perspectives from experts and global Smart Grid initiatives.						
Unit-IISmart Grid Technologies8 Hrs						
Technology Drivers, Smart energy resources, Smart substations, Substation Automatic)n,					
Feeder Automation ,Transmission systems: EMS, FACTS and HVDC, Wide area monitorin	ıg,					
Protection and control, Distribution systems: DMS, Volt/VAR control, Fault Detection)n,					
Isolation and service restoration, Outage management, High Efficiency Distributi	on					
Transformers, Phase Shifting Transformers, Plug in Hybrid Electric Vehicles (PHEV).						
Unit –III Smart Meters I0 Hrs						
Introduction to Smart Meters, Advanced Metering infrastructure (AMI) drivers and benefits	\$,					
AMI protocols, standards and initiatives, AMI needs in the smart grid, Phasor Measuremer	it					
Unit(PMU), Intelligent Electronic Devices(IED) & their application for monitoring d	Z					
Unit -IV Power Quality Management in Smart Crid 10 Hrs						
Dower Quality & EMC in Smort Crid. Dower Quality issues of Crid connected Denowable						
Fower Quality & ENC III Small Old, Fower Quality Issues of Old connected Renewable						
Energy Sources, Power Quality Conditioners for Smart Grid, web based Power Quality						
Unit –V High Performance Computing 10 Hrs						
Local Area Network (LAN), House Area Network (HAN), Wide Area Network	k					
(WAN).Broadband over Power line (BPL). IP based Protocols. Basics of Web Service an	d					
WAN), Broadband over Power line (BPL), IP based Protocols, Basics of Web Service and						

On completion of this course, student will be able to

- Understand the concepts and design of Smart grid.
- Understand the various communication technologies in smart grid.
- Understand the various measurement technologies in smart grid.
- Understand the analysis and stability of smart grid.
- Learn the renewable energy resources and storages integrated with smart grid.
- familiarize the high performance computing for Smart Grid applications

Textbooks:

- 1. Smart Grid, Janaka Ekanayake, Liyanage, Wu, Akihiko Yokoyama, Jenkins, Wiley Publications, 2012, Reprint 2015.
- 2. Smart Grid: Fundamentals of Design and Analysis, James Momoh, Wiley, IEEE Press., 2012, Reprint 2016.

- 1. The Smart Grid Enabling Energy efficiency and demand response, Clark W. Gellings, P.E., CRC Press, Taylor & Francis group, First Indian Reprint. 2015.
- 2. Smart Grid Applications, Communications, and Security Edited by Lars Torsten Berger, Krzysztof Iniewski, WILEY, 2012, Reprint 2015.
- 3. Practical Electrical Network Automation and Communication Systems, Cobus Strauss, ELSVIER, 2003



		Indust	rial Electronics				
Course Code	L:T:P:S	Credits	Exam Marks	Exam Dura	tion Course Type		
22A0433T	3: 0:0:0	3	CIE: 30 SEE:70	3Hours	OEC		
Course Objectiv	ves:				·		
The course should	d enable the st	udents to:					
• Describe	semi-conducto	or devices (such as PN junction	on diode & 7	Fransistor) and their		
switching	characteristic	s.					
• Understan	d the characte	eristics of A	C to DC converters	•			
• Understan	d about the pr	actical appl	ications Electronics	s in industries	5.		
• Describe t	he ultrasonic	and its appli	cation.				
Syllabus					Total Hours: 48		
Unit-I		Industri	al Electronics		10 Hrs		
Scope of industrial Electronics, Semiconductors, Merits of semiconductors, crystalline structure, Intrinsic semiconductors, Extrinsic semiconductors, current flow in semi conductor, Open circuited p-n junction, Diode resistance, Zener diode, Photo conductors and junction what diades. Photo walking effect Light emitting diades (LED)							
Unit-II		<u>Tr</u>	ansistor).	8 Hrs		
Introduction, The circuited transisto Currents in a tran resistance, Tran semiconductor De static characterist transistor in comr	junction tran or, Transistor isistor, Emitte sistor as an evices, Chara- ic curves of non collector	sistor, Conv biased in the r efficiency a amplifien cteristic cur PNP junctic Configuration	entions for polariti ne active region, C , Transport factor a c, Transistor con ves of junction tra- on transistor in cor on.	es of voltage urrent compo and transistor struction, L nsistor in cor nmon emitte	s and currents, Open onents in transistors, $-\alpha$, Dynamic emitter setter symbols for nmon configuration, r configuration, The		
Unit –III		AC to D	OC converters		10 Hrs		
AC to DC converters- Introduction, Classification of Rectifiers, Half wave Rectifiers, Full wave Rectifiers, Comparison of Half wave and full wave rectifiers, Bridge Rectifiers, Bridge multiplying Rectifier circuits, Capacitor filter, LC Filter, Metal Rectifiers, Regulated Power Supplies, Classification of Voltage Regulators, Short period Accuracy of Regulators, Long period .Accuracy of Voltage Regulator, Principle of automatic voltage Regulator, Simple D.C. Voltage stabilizer using Zener diode, D.C. Voltage Regulators, Series Voltage Regulators, Complete series voltage regulator circuit, Simple series voltage regulator.							
Unit -IV		Resistance	welding controls		10 Hrs		
Resistance weldi A.C. resistance w Resistance weldi:	ng controls: relding, Types ng, Energy s	Introduction of Resistan torage weld	n, Resistance weldince welding, Electring. Induction hea	ng process, H onic welding ating: Princip	Basic Circuit for control used in ble of induction		
heating, Theory o	of Induction h	eating merit	s of induction heat	ing, Applicat	ion of induction		

heating, High frequency power source of induction heating. Dielectric heating: Principle of

dielectric heating, theory of dielectric heating, dielectric properties of typical materials, electrodes used in dielectric heating, method of coupling of electrodes to the R.F. generator, Thermal losses in Dielectric heating, Applications.

Unit –V	Ultrasonics	10 Hrs						
Ultrasonics: Introduction, Generation of Ultrasonic waves, Application of Ultrasonic waves,								
Ultrasonic strobos	Ultrasonic stroboscope, ultrasonic as means of communication, ultrasonic flaw detection,							
Optical image on 1	Optical image on non-homogeneities, ultrasonic study of structure of matter, Dispersive study							
of structure of ma	atter, Dispersive and colloidal effect of Ultrasonic, Co	agulating action of						
Ultrasonic, separa	ation of mixtures by ultrasonic waves, cutting and	machining of hard						
materials by ultras	sonic vibrations, Degassing of liquids by ultrasonic wav	es, Physio-chemical						
effects of ultrasoni	ics, chemical effects of ultrasonics, Thermal effects of u	ltrasonics, soldering						
and welding by ult	trasonics, Ultrasonic Drying							

Course Outcomes (CO):

On completion of this course, student will be able to

- Understand the semi-conductor devices and their switching characteristics.
- Apply the Ultrasonic waves with different applications.
- Understand the working of Transistor and its different configurations.
- Analyze the thermal effects of ultrasonic, soldering and welding by ultrasonic, ultrasonic Drying in the industry; interpret the characteristics of AC to DC converters.
- Develop the practical applications Electronics in industries.
- Apply the process of Resistance welding, Induction heating and Dielectric heating in the industry.

Textbooks:

- Fundamentals of Industrial Electronics, Bogdan M Wilamowski, J David irwin, 2nd Edition, 2011.
- 2. Industrial and Power Electronics G. K. Mithal and Maneesha Gupta, Khanna Publishers, 19th Ed., 2003.
- 3. Integrated Electronics J. Millman and C.C Halkias, McGraw Hill, 1972.

- 1. Electronic Devices and circuits Theodore. H. Bogart, Pearson Education, 6th Edn., 2003.
- 2. Integrated Circuits and Semiconductor Devices Deboo and Burroughs, ISE



		Clou	ld Computing			
Course Code	L:T:P:S	Credits	Exam Marks	Exam Dura	tion Course T	ype
22A0529T	3: 0:0:0	3	CIE: 30 SEE:70	3Hours	OEC	
Course Objecti	ves:		1	1		
The course should	d enable the st	tudents to:				
To introdu	ice the broad	perceptive o	of cloud architecture	e and model		
• To unders cloud.	stand the cor	ncept of Vin	rtualization and fai	miliar with 1	the lead players	s in
• To unders model	tand the featu	res of cloud	l simulator and app	bly different	cloud programm	ning
To design	of cloud Serv	vices and exp	plore the trusted clo	oud Computin	ng system	
Syllabus					Total Hours:4	8
Module-I		Basics of C	Cloud Computing		10Hrs	
Introduction to Cloud : Introduction to Cloud, Cloud Computing Reference Model, Characteristics and Benefits, Challenges Ahead, Elasticity in Cloud, On-demand Provisioning. Virtualization : Introduction, Characteristics of Virtualized Environment, Taxonomy of						
Module-II	Cloud	Architectu	re. Models and Se	-s. curity	9Hrs	
Cloud Computi Infrastructure / H Clouds. Cloud Deploym	ing Archited ardware as a ent Model:	e ture : Intro Service, Pla Public Clo	duction, Cloud H tform as a Service, uds, Private Cloud	Reference M Software as ds, Hybrid (lodel, Architec a Service, Type Clouds, Commu	ture, es of unity
Module-III		iu. 1 Technoloc	ties and Advancen	ients	10Hrs	
Apache Hadoop, Programming En	Module-IIICloud Technologies and Advancements10HrsApache Hadoop, MapReduce, Hadoop Cluster setup, Virtual Box, Google App Engine, Programming Environment for Google App Engine – Open Stack10Hrs					
Module-IV		VMwa	re Simulator		9Hrs	
VMWare: Basic	s of VMWar	e, Advantag	ges of VMware vir	tualization,	create a new vi	rtual
machine on local stopping a virtual	host, clonin machine.	g virtual ma	achines, virtualize	a physical m	achine, starting	and
Module-V		Cloud	Applications		10Hrs	
Cloud Application Business And Applications, and	ons: Scientific Consumer A	e Applicatio Applications Online Gam	ns – Health Care, C s - CRM and El ing.	deoscience. RP, Social	Networking, M	ledia

On completion of this course, student will be able to

- To Understand the basic concepts about cloud computing vision and its developments and gain the Knowledge of virtualization technology.
- Analyze the concepts of cloud services and the deployment models.
- Choose among various cloud technologies for implementing applications (GAE, Open stack ,etc)
- Construct the virtual machines by using VMware simulator.
- Build scientific applications by using Cloud environment.
- Develop Business and Consumer Applications.

Textbooks:

- 1. Mastering Cloud Computing by RajkumarBuyya, Christian Vecchiola, S.Thamarai Selvi from TMH 2013.
- 2. George Reese, "Cloud Application Architectures: Building Applications and Infrastructure in the Cloud" O'Reilly
- 3. Cloud computing a practical approach Anthony T.Velte , Toby J. Velte Robert Elsenpeter, TATA McGraw- Hill , New Delhi 2010.

Reference Books:

- 1. Cloud computing for dummies- Judith Hurwitz , Robin Bloor , Marcia Kaufman ,Fern Halper, Wiley Publishing, Inc, 2010
- 2. Cloud Computing (Principles and Paradigms), Edited by Rajkumar Buyya, James Broberg, Andrzej Goscinski, John Wiley & Sons, Inc. 2011
- 3. Enterprise Cloud Computing, Gautam Shroff, Cambridge University Press, 2010.
- 4. Cloud Application Architectures: Building Applications and Infrastructure in the Cloud, George Reese, O 'Reilly, SPD, rp2011.
- **5.** Essentials of Cloud Computing by K. Chandrasekaran. CRC Press. Cloud computing A Hands-On Approach by ArshdeepBahga and Vijay Madisetti.

Web Resources:

- 1. <u>https://nptel.ac.in/courses</u>
- 2. https://freevideolectures.com/university/iitm



Construction Management						
Course Code	L:T:P:S	Credits	Exam Marks	Exam Durat	ion Course Ty	pe
22A0152T	3: 0:0:0	3	CIE: 30 SEE:70	3Hours	OEC	
Course Objecti	ves:	•		1		
The course shoul	d enable the st	tudents to:				
• To make	the student far	niliar with v	arious construction	activities, pre	paring	
constructi	on schedule a	nd maintain	ing documents and	records of tho	se activities	
To teach t	the students al	out various	terms and technolo	gies involved	in earthwork of	
constructi	on activities			8		
To make 1	the students fa	miliar with	concents involved i	in project man	agement like bar	r
charts and	l milestone ch	arts		in project man		
To teach t	the students th	e concents o	of time estimates in	volved in CPN	A and PERT flo	vat
and slack	critical nath (colculations	fi time estimates m			'ai
Syllabus				r	Lotal Hours 17	
INIT I	Fundan	nontals Of (⁷ onstruction Tool	nology	12 Urs	
UNII - I	rundan	nentais Of C	construction Tech	nology		
Works – Constru	Jiscussion – C	Construction	truction Schedule	– Productivity	v and Mechanize	on ed
Construction – C	onstruction D	ocuments –	Construction Reco	ords – Quality	- Safety - Code	es
and Regulations.					2	
UNIT - II		Ea	rthwork		10 Hrs	
Classification of	Soils – Projec	t Site – Dev	elopment – Setting	Out - Mechan	ized Excavation	. —
Groundwater Co	ontrol – Trer	nchless (No	o-dig) Technology	– Grading	 Dredging.Roc 	ck
Excavation – Bas	ic Mechanics	of Breakage	e – Blasting Theory	v – Drillability	of Rocks – Kind	ds
of Drilling – Se	election of the	e Drilling I	Method and Equip	oment – Expl	osives – Blastin	ıg
Patterns and Firir	<u>ig Sequence –</u>	Smooth Bla	sting – Environme	ntal Effect of	Blasting	
UNIT - III	Project Man	agement a	nd Bar Charts And	d Milestone	10 Hrs	
			Charts			
Project planning	- Scheduling	g – Controll	ing – Role of dec	ision in proje	ect management	-
Techniques for	analyzing alt	ternatives (Operation research	– Methods	of planning an	ıd
programming pro	blems – Deve	elopment of	bar chart – Illustrat	ive examples	– Shortcomings of	of
bar charts and rer	nedial measur	<u>es – Milesto</u>	one charts			
UNIT - IV	Elements of	Network a	nd Development (Of Network	12 Hrs	
Introduction – E	vent – Activi	ty – Dumm	ıy – Network rules	s – Graphical	guidelines for	
network – Com	mon partial s	situations in	n network – Num	bering the ev	ents – Cycles	
Problems						
UNIT - V		PER	I and CPM		12 Hrs	
Time estimates –	Frequency d	istribution -	- Mean, variance a	nd standard d	eviation-Expecte	ed
time Problems -	time Problems -Earliest expected time – Formulation for TE - Latest allowable occurrence					
time – Formulat	10n IOr IL -	Combined	tabular computati	ons for IE a	ind IL problem	is.
ntroduction - Slack – Critical path-Illustrative examples Problems						

On completion of this course, student will be able to

- Identify the various construction activities like preparing construction schedule and maintaining documents and records of those activities
- Understand the concepts and techniques involved in earthwork activities• To understand about the emerging infectious diseases and aids their management
- Understand the steps involved in developing a project scheduling and management and the application of bar charts and milestone charts.
- Understand the various elements of a network diagram like event, activity and dummy.
- Understand the concepts of calculation of time estimates of CPM and PERT

Textbooks:

- Construction project management by Jha ,Pearsonpublications, New Delhi 2nd Edition 2015
- 2. Construction Technology by SubirK.Sarkar and SubhajitSaraswati Oxford Higher EducationUniv.Press, Delhi 2008 edition
- 3. Project Planning and Control with PERT and CPM by Dr.B.C.Punmia, K.K.Khandelwal, Lakshmi Publications New Delhi 2022 editionDelhi

1. Reference Books:

- 1. Optimal design of water distribution networks P.R.Bhave, Narosa Publishing house 2003.
- 2. Total Project management, the Indian context- by : P.K.JOY- Mac Millan Publishers India Limited.

E-resources:

1. https://nptel.ac.in/courses/105104161



Electric Vehicles							
		(Common	to all Except EEE)				
Course Code	L:T:P:S	Credits	Exam Marks	Exam Dura	tion	Course Type	
22А0232Та	3: 0:0:0	3	CIE: 30 SEE:70	3Hours		OEC	
Course Objecti	ves:	1	l		I		
The course should	d enable the st	tudents to:					
Understand	1 to Provide go	od foundatio	n on hybrid and elect	trical vehicles.			
 Understand to Frovide good roundation on hybrid and electrical vehicles. Understand To address the underlying concepts and methods behind power transmission in hybrid and electrical vehicles 							
Familiarize	e energy storage	e systems for \cdot	electrical and hybrid	transportation	1	1 * 1	
• Design an	d develop bas	ic schemes	of electric vehicles	and hybrid e		c venicles.	
Syllabus	L				Tota	I Hours: 50	
Module-I	Electric Veh	icle Propul	sion and Energy S	ources		10Hrs	
fundamentals propulsion system design - force velocity characteristics, calculation of tractive power and energy required, electric vehicle power source - battery capacity, state of charge and discharge, specific energy, specific power, Ragone plot. battery modeling - run time battery model, first principle model, battery management system- soc measurement, battery cell balancing. Traction batteries - nickel metal bydride battery. Li-Ion. Lipolymer battery							
Module-II	Electr	ic Vehicle P	Power Plant And D	Drives		10 Hrs	
switch reluctance converter, isolate PWM, current co control	e machines. I d DC/DC con ontrol method	Power electro verter. Two . Switch rel	ronic converters-D quadrant chopper a luctance machine d	C/DC conve and switching lrives - volta	rters g mod	- buck boost les. AC drives ontrol, current	
Unit -III	Hy	brid And E	lectric Drive Trai	ns		9 Hrs	
Introduction hybritrains in energy s topologies. Powe DC motor drive reluctance motor	Introduction hybrid electric vehicles, history and social importance, impact of modern drive trains in energy supplies. Hybrid traction and electric traction. Hybrid and electric drive train topologies. Power flow control and energy efficiency analysis, configuration and control of DC motor drives and induction motor drives, permanent magnet motor drives, switch						
Unit -IV	Electric	and Hybri	d Vehicles - Case S	Studies		11 Hrs	
Parallel hybrid, series hybrid -charge sustaining, charge depleting. Hybrid vehicle case study – Toyota Prius, Honda Insight, Chevrolet Volt. 42 V system for traction applications. Lightly hybridized vehicles and low voltage systems. Electric vehicle case study - GM EV1, Nissan Leaf, Mitsubishi Miev. Hybrid electric heavy duty vehicles, fuel cell heavy							
Unit -V	Elec	ctric And H	ybrid Vehicle Des	ign		10 Hrs	
Introduction to combustion engir energy storage t strategies in hyb comparison, impl	hybrid vehicl ne. Sizing of p echnology, c rid and elect ementation.	le design.] propulsion m ommunicati cric vehicles	Matching the electronotor, power electronotor, supporting subsection of a supporting subsection of a support	tric machine onics, drive s ubsystem. En ement strateg	e and ystem nergy gies-	the internal n. Selection of management classification,	

On completion of this course, student will be able to

- Understand the working of hybrid and electric vehicles
- Apply a suitable drive scheme for developing an hybrid and electric vehicles depending on resources
- e Develop the electric propulsion unit and its control for application of electric vehicles.
- Understand the proper energy storage systems for vehicle applications
- Design and develop basic schemes of electric vehicles and hybrid electric vehicles

Textbooks:

- 1. Iqbal Hussein, "Electric and Hybrid Vehicles: Design Fundamentals", 2nd edition, CRC Press, 2003.
- 2. Amir Khajepour, M. Saber Fallah, Avesta Goodarzi, "Electric and Hybrid Vehicles: Technologies, Modeling and Control - A Mechatronic Approach", illustrated edition, John Wiley & Sons, 2014.
- 3. Mehrdad Ehsani, YimiGao, Sebastian E. Gay, Ali Emadi, "Modern Electric, Hybrid Electric and Fuel Cell Vehicles: Fundamentals, Theory and Design", CRC Press, 2004.

- 1. James Larminie, John Lowry, "Electric Vehicle Technology", Explained, Wiley, 2003.
- 2. John G. Hayes, G. Abas Goodarzi, "Electric Powertrain: Energy Systems, Power Electronics and Drives for Hybrid, Electric and Fuel Cell Vehicles", 1st edition, WileyBlackwell, 2018.



		Basics	of VLSI Design		
Course Code	L:T:P:S	Credits	Exam Marks	Exam Durat	ion Course Type
22A0432T	3: 0:0:0	3	CIE: 30 SEE:70	3Hours	OEC
Course Objecti	ves:				
The course should	d enable the st	tudents to:			
• To give ex	xposure to dif	ferent steps	involved in fabrica	ation Process of	of PMOS & NMOS
	$\frac{1}{2}$, CIVIOS & D		ners.		1
• 10 provid	e knowledge	on electrical	vith various loads	s & BICMUS	, devices to analyze
		an Degia Cir	with various loads	I SI Desian	
• To provid	the design D	ulas and dm	cult Concepts of v	LSI Design	it and hasis sinewit
• To apply	the design R	ta	aw layout of a giv	en logic circu	it and basic circuit
	the design for	us. r tostobility i	mathada far aamhi	national & sag	uontial CMOS
• 10 Apply	the design for			lational & seq	uential CiviOS
Syllabus				r	Lotal Hours: 50
Module-I	Inti	oduction to	Fabrication Proc	-	10Hrs
Introduction: Brie	ef Introductio	n to IC tech	nology, Moore's I	Law, Different	modes MOSFET
operation, Fabrica	ation Process	of PMOS, 1	NMOS, CMOS &	B1-CMOS dev	/ices, Comparison
between CMOS a	ind Bi-polar I	echnologies	S.		
Fabrication Step	ps: Wafer	Preparation	, Oxidation, Ph	otolithography	7, Etching, Ion
Implantations, Me	etallization, T	esting.			
Module-II	Basic El	ectrical Pro	perties of MOS/B	iCMOS	10 Hrs
		(devices		
Basic Electrical	Properties:	Ids Vs Vds	relationships, MO	S transistor T	hreshold Voltage-
VT, figure of m	erit- $\omega 0$, Tran	sconductanc	ce - gm, Output c	onductance-go	ls, Pass transistor
logic, NMOS In	verter, Pull-u	p to Pull-de	own Ratio for NM	IOS inverter	driven by another
NMOS inverter,	and through o	one or more	pass transistors V	arious pull up	s, CMOS Inverter
analysis and desig	gn, Bi-CMOS	Inverters.			
Unit -III		Basic Ci	rcuit Concepts		9 Hrs
Basic Circuit Co	ncepts: Sheet	Resistance	Rs and its concept	ots to MOS, A	Area Capacitances
calculations, Inve	erter Delays,	Driving larg	ge Capacitive Load	ls, Wiring Ca	pacitances, Fan-in
and fan-out					
Unit -IV	V V	LSI Circui	t Design Processes	8	11 Hrs
VLSI Design Flo	ow, MOS Lag	yers, Stick	Diagrams, Design	Rules and La	yout, Lambda(λ)-
based design rul	es for wires,	contacts an	nd Transistors, La	yout Diagram	s for NMOS and
CMOS Inverters	Logic Gate	s and Vari	ious MOS Circuit	s. Scaling	of MOS circuits,
Limitations of Sc.	aling.				

Unit -	V CMOS Testing	10 Hrs						
CAD T	CAD Tools for Design and Simulation, Aspects of Design Tools, Design for Testability,							
Testing	Festing Combinational Logic, Testing Sequential Logic, Practical Design for Test (OFT)							
Guideli	nes, Scan Design Techniques, Built-In-Self-Test (BIST), Future Tr	ends.						
Course	Outcomes (CO):							
On con	pletion of this course, student will be able to							
•	Acquire qualitative knowledge about the fabrication process of inte	egrated circuit using						
	MOS transistors.							
•	Understand the concept of Basic Electrical Properties of MOS/Bi-G	CMOS Devices						
•	Apply the basic circuit concepts to MOS circuits.							
•	Understand the concept of Scaling of MOS circuits and Limitation	s of Scaling						
•	Apply the design Rules to draw the Stick diagram &layout of a giv	en logic circuit.						
•	nterpret the need for testability and testing methods in VLSI.							
Textbo	oks:							
1.	Kamran Eshraghian, "Essentials of VLSI Circuits and Systems", D	ouglas and A.						
	Pucknell and SholehEshraghian, Prentice-Hall of India Private Lim	ited, 2005 Edition.						
2.	Behzad Razavi, "Design of Analog CMOS Integrated Circuits", N	lcGraw Hill, 2003						
3.	Modern VLSI Design – Wayne Wolf, 3 Ed., 1997, Pearson Educat	ion.						
Referei	ce Books:							
1.	an M. Rabaey, "Digital Integrated Circuits", AnanthaChandrakasa	n and Borivoje						
-	Nikolic, Prentice-Hall of India Pvt.Ltd, 2nd edition, 2009.							
2.	John P. Uyemura, "Introduction to VLSI Circuits and Systems", Jo	hn Wiley & Sons,						
	reprint 2009							
3.	CMOS VLSI Design-A Circuits and Systems Perspective, Neil H.I	E Weste, David						
	Harris, Ayan Banerjee, 3rd Edn, Pearson, 2009.							



Introduction to Cyber Security						
Course Code	L:T:P:S	Credits	Exam Marks	Exam Dura	tion	Course Type
22A0534b	3: 0:0:0	3	CIE: 30 SEE:70	3Hours		OEC
Course Objecti	ves:				•	
The course should	d enable the st	tudents to:				
 The Cyber principles, and IS tec Students v of Cyber S Evaluate t 	r security Cou , Security arcl hnologies. vill gain insig Security profe he trends and	rse will provintecture, ris ht into the ir ssionals. patterns tha	vide the students w k management, atta nportance of Cyber t will determine the	ith foundation acks, incident Security and future state	nal Cy s, and l the in of cyb	vber Security emerging IT ntegral role per security.
Svllabus		1			Total	Hours:48
Module-I		Introductio	on to Cybercrime			9 Hrs
Introduction to Cybercrime: Definition and Origins of the Word, Cybercrime and Information Security, Who are Cybercriminals, Classifications of Cybercrimes, Cybercrime: The Legal Perspectives, Cybercrimes: An Indian Perspective, Cybercrime and the Indian ITA 2000, A Global Perspective on Cybercrimes, Cybercrime Era: Survival Mantra for the Netizens						
Module-II		Cybe	er Offenses			10 Hrs
How Criminals	Plan Them	-Introducti	on, How Crimin	als Plan th	e At	tacks, Social
Engineering, Cyb	er stalking, C	yber Cafe aı	nd Cybercrimes, Bo	otnets: The Fu	uel foi	r Cybercrime,
Attack Vector Ba	ckdoors-Stega	anography-S	QL Injection.			
Module-III	Cyber	crime Mobi	le and Wireless D	evices		9 Hrs
Introduction, Pro	liferation of N	Nobile and Y	Wireless Devices,	Trends in Mo	obility	, Credit Card
Frauds in Mobil	e and Wirel	ess Comput	ting Era, Security	Challenges	Pose	d by Mobile
Devices, Registry	v Settings for	Mobile Dev	vices, Authentication	on Service Se	ecurit	y, Attacks on
Mobile/Cell Phon	es, Mobile D	evices: Secu	rity Implications for	or Organizatio	ons, C	Organizational
Measures for Han	dling Mobile					
Module-IV	Tools	and Metho	ds Used in Cyberc	rime		10Hrs
Introduction, Prox	xy Servers and	d Anonymiz	ers, Phishing, Pass	word Crackin	ıg, Ke	y loggers and
Spywares, Virus	and Worms, 7	Frojan Hors	es and Backdoors,	DoS and DD	os A	ttacks, Buffer
Overflow, Attack	s on Wireless	Networks, I	Phishing and Identi	ty Theft: Intro	oducti	ion, Phishing,
Identity Theft (ID Theft).						
Module-V		Cyber Crit	mes and security			10Hrs
Cyber Security –	Organizationa	l implication	ns-cost of cybercrit	mes and IPR	issue	s Web threats
for organizations	s: the evils	and Perils	-Social media ma	arketing Sec	urity	and privacy
Implications-Prot	ecting people	e privacy i	n the organization	ns Forensic	best	practices for
organizations. Ca	ses.					

On completion of this course, student will be able to

- Cyber Security architecture principles
- Identifying System and application security threats and vulnerabilities
- Identifying different classes of attacks
- Cyber Security incidents to apply appropriate response
- Describing risk management processes and practices

Textbooks:

- 1. Cyber Security: Understanding Cyber Crimes, Computer Forensics and Legal Perspectives, Nina Godbole, SunitBelapure, Wiley.
- 2. Principles of Information Security, MichealE.Whitman and Herbert J.Mattord, Cengage Learning

Reference Books:

1. Information Security, Mark Rhodes, Ousley, MGH.



			Operations Researc				
Course Code	L:T:P:S	Credits	Exam Marks	Exam Dura	tion	Course Type	
22A0335T	2: 1:0:0	3	CIE: 30 SEE:70	3Hours		PCC	
Course Object	ives:		•				
• To impar	t the basic	concepts of	modelling, models an	nd statements of	of the	operations	
research.							
Formulat	e and solve	linear prog	ramming problem/sit	uations.			
Model st	rategic beha	avior in diff	erent economic situat	tions.			
To solve	transportati	on problem	s to minimize cost.				
Apply Q bookings	ueuing theo etc.	ry to solve	problems of traffic co	ongestion, cour	nters in	n banks, railway	
• Explain s	cheduling a	and sequence	ing of production run	ns and develop	prope	r replacement	
Syllabus					Tota	Hours:42	
UNIT - I		Int	roduction to OR			12 Hrs	
Introduction to	Operation	s Research	(OR): OR definition	1 - Classificatio	on of N	Aodels,	
modeling – Metl	nods of solv	ing OR Mo	dels, limitations and	applications of	f OR n	nodels	
Linear Program	nming(LP)	• Problem F	ormulation Graphic	al Method Sin	nlev l	Method Big-	
M Method Two	Phase Sirr	nlex Metho	of Special Cases of J	P- Degenerac	v Infe	easibility and	
Multiple Optima	1 Solutions	Concept of	f dual theorem	Li Degenerae	<i>y</i> , III	casionity and	
UNIT - II		nsportation	and Assignment P	roblems		10 Hrs	
Transportation F	Problem – F	Formulation	· Different Methods	of Obtaining	Initial	Basic Feasible	
Solution –North	West Co	mer Rule.	Least Cost Method	Vogel's Apr	roxim	Duble 1 cubible	
Optimality Met	Solution –North West Corner Rule, Least Cost Method, Vogel's Approximation Method;						
Deptimativy Method – Modified Distribution (MODI) Method; Special Cases – Ofioaranced							
Transportation F	10d – Mod Problem, De	ified Distri	bution (MODI) Met oblem. Assignment	hod; Special Problem – For	Cases mulat	ation Method; – Unbalanced ion, Hungarian	
Transportation F Method for Solv	rod – Mod Problem, De ing Assigni	ified Distri egenerate Pi nent Proble	bution (MODI) Met oblem. Assignment ms, Traveling Salesn	hod; Special Problem – For nan problem.	Cases mulat	ation Method; – Unbalanced ion, Hungarian	
Transportation F Method for Solv UNIT - III	roblem, De ing Assigni	egenerate Pr nent Proble Game the	bution (MODI) Met oblem. Assignment ms, Traveling Salesn ory & Job Sequenci	hod; Special Problem – For nan problem.	Cases mulat	ation Method; – Unbalanced ion, Hungarian 10 Hrs	
Transportation F Method for Solv UNIT - III Game theory: 0	roblem, De ing Assigni	egenerate Pr nent Proble Game the	bution (MODI) Met roblem. Assignment ms, Traveling Salesn ory & Job Sequenci person zero sum gar	hod; Special Problem – For nan problem. ing	Cases mulat	ation Method; – Unbalanced ion, Hungarian 10 Hrs 1 min max	
Transportation F Method for Solv UNIT - III Game theory: C principle, Game:	roblem, De ing Assigni ptimal solu	regenerate Present Problement Proble Game the string of two ddle points.	bution (MODI) Met oblem. Assignment ms, Traveling Salesn ory & Job Sequenci person zero sum gan mixed strategies. Re	hod; Special Problem – For nan problem. ing nes, the max meduction by pri	Cases mulat	ation Method; – Unbalanced ion, Hungarian 10 Hrs 1 min max s of dominance.	
Transportation F Method for Solv UNIT - III Game theory: C principle. Games arithmetic, algeb	Problem, De ing Assigni ptimal solu s without sa	egenerate Proble ment Proble Game the ation of two ddle points and graph	bution (MODI) Met roblem. Assignment ms, Traveling Salesn ory & Job Sequenci person zero sum gan mixed strategies. Re ical method.	hod; Special Problem – For nan problem. ing nes, the max m eduction by pri	Cases mulat	ation Method; – Unbalanced ion, Hungarian 10 Hrs 1 min max s of dominance,	
Transportation F Method for Solv UNIT - III Game theory: C principle. Games arithmetic, algeb	Problem, De ing Assigni ptimal solu s without sa raic methoo	ified Distri- egenerate Prinent Proble Game the ition of two ddle points d and graph	bution (MODI) Met roblem. Assignment ms, Traveling Salesn ory & Job Sequenci person zero sum gan mixed strategies. Re- ical method.	hod; Special Problem – For nan problem. ing nes, the max meduction by pri	Cases mulat	ation Method; – Unbalanced ion, Hungarian 10 Hrs 1 min max s of dominance, mag. Solution of	
Transportation F Method for Solv UNIT - III Game theory: C principle. Games arithmetic, algeb Job Sequencing	Problem, De Problem, De ing Assigni ptimal solu s without sa raic methoo g: Introduct	ified Distri- egenerate Prinent Proble Game the ition of two ddle points d and graph	bution (MODI) Met roblem. Assignment ms, Traveling Salesn ory & Job Sequenci person zero sum gan mixed strategies. Re ical method.	hod; Special Problem – For nan problem. ing nes, the max m eduction by pri flow shop sch	Cases mulat	ation Method; – Unbalanced ion, Hungarian 10 Hrs 1 min max s of dominance, ng, Solution of sing of n Jobs	
Transportation F Method for Solv UNIT - III Game theory: C principle. Games arithmetic, algeb Job Sequencing Job Sequencing	Problem, De ing Assigni Optimal solu s without sa praic methoo g: Introduct Problem, H	ified Distri- egenerate Prinent Proble Game the ition of two ddle points, d and graph- ion to Job s Processing of cal method	bution (MODI) Met roblem. Assignment ms, Traveling Salesm ory & Job Sequenci person zero sum gan mixed strategies. Re- ical method. shop Scheduling and of n Jobs through tw	hod; Special Problem – For nan problem. ing nes, the max m eduction by pri flow shop sch o machines, I	Cases mulat nin and nciple nedulir Process	ation Method; – Unbalanced ion, Hungarian 10 Hrs 1 min max s of dominance, ng, Solution of sing of n Jobs	
Transportation F Method for Solv UNIT - III Game theory: C principle. Games arithmetic, algeb Job Sequencing Job Sequencing through m mach	Problem, De ing Assigni Optimal solu s without sa raic methoo g: Introduct Problem, H ines, graphi	ified Distri- egenerate Pre- ment Proble Game the tion of two ddle points d and graph ion to Job se Processing of cal method	bution (MODI) Met roblem. Assignment ms, Traveling Salesn ory & Job Sequenci person zero sum gan mixed strategies. Re- ical method. shop Scheduling and of n Jobs through tw	hod; Special Problem – For nan problem. ing nes, the max meduction by pri flow shop sch vo machines, H	Cases mulat nin and nciple nedulir Process	ation Method; – Unbalanced ion, Hungarian 10 Hrs 1 min max s of dominance, ng, Solution of sing of n Jobs 12 Hrs	
Transportation F Method for Solv UNIT - III Game theory: C principle. Games arithmetic, algeb Job Sequencing Job Sequencing through m mach UNIT - IV	Problem, De ing Assignt Optimal solu s without sa oraic methoo g: Introduct Problem, H ines, graphi	ified Distri- generate Prinent Proble Game the dition of two ddle points and graph ion to Job s Processing of cal method ueuing The	bution (MODI) Met roblem. Assignment ms, Traveling Salesm ory & Job Sequenci person zero sum gan mixed strategies. Re- ical method. shop Scheduling and of n Jobs through two eory & Inventory Co- inology. Arrival Patt	hod; Special Problem – For nan problem. ing nes, the max m eduction by pri flow shop sch o machines, H	Cases mulat: nin and nciple redulir Process	ation Method; – Unbalanced ion, Hungarian 10 Hrs d min max s of dominance, ng, Solution of sing of n Jobs 12 Hrs Population	
Transportation F Method for Solv UNIT - III Game theory: C principle. Games arithmetic, algeb Job Sequencing Job Sequencing through m mach UNIT - IV Queuing Theor Departure Patter	Problem, De ing Assigni Optimal solu s without sa raic methoo g: Introduct Problem, H ines, graphi y: Introduct	ified Distri- egenerate Pre- nent Proble Game the diand graph ion to Job sector cal method ueuing The ion – Term	bution (MODI) Met roblem. Assignment ms, Traveling Salesm ory & Job Sequenci person zero sum gan mixed strategies. Re- ical method. shop Scheduling and of n Jobs through tw eory & Inventory Co- inology, Arrival Patto- irth & Death Process	hod; Special Problem – For nan problem. ing nes, the max m eduction by pri flow shop sch o machines, H ontrol ern, Service Cl Single Chann	Cases mulat nin and nciple nedulir Process nannel	ation Method; – Unbalanced ion, Hungarian 10 Hrs l min max s of dominance, ng, Solution of sing of n Jobs 12 Hrs , Population, dels with	
Transportation F Method for Solv UNIT - III Game theory: C principle. Games arithmetic, algeb Job Sequencing through m mach UNIT - IV Queuing Theor Departure Patter Poisson Arrivals	Problem, De ing Assigni Optimal solu s without sa oraic methoo g: Introduct Problem, H ines, graphi Q y: Introduct n, Queue D	and graph ion to Job s Processing of cal method ueuing The ion – Term iscipline, B	bution (MODI) Met roblem. Assignment ms, Traveling Salesn ory & Job Sequenci person zero sum gan mixed strategies. Re- ical method. Shop Scheduling and of n Jobs through tw eory & Inventory Co- inology, Arrival Patte irth & Death Process Fimes with infinite ar	hod; Special Problem – For nan problem. ing nes, the max m eduction by pri flow shop sch to machines, H ontrol ern, Service Cl , Single Chann of finite queue	Cases mulat: nin and nciple nedulir Process nannel nel Mo lenoth	ation Method; – Unbalanced ion, Hungarian 10 Hrs I min max s of dominance, ng, Solution of sing of n Jobs 12 Hrs , Population, dels with h: Multichannel	
Transportation F Method for Solv UNIT - III Game theory: C principle. Games arithmetic, algeb Job Sequencing through m mach UNIT - IV Queuing Theor Departure Patter Poisson Arrivals Models with Poi	Problem, De ing Assigni ptimal solu s without sa praic methoo g: Introduct Problem, I ines, graphi y: Introduct n, Queue D , Exponenti sson Arriva	ified Distri- egenerate Prinent Proble Game the distance of two ddle points, and graph ion to Job se Processing of cal method ueuing The ion – Term iscipline, B al Service T ls, Exponentiation of the content of two distance of two second second second content of two distance of two dis	bution (MODI) Met roblem. Assignment ms, Traveling Salesm ory & Job Sequenci person zero sum gan mixed strategies. Re- ical method. shop Scheduling and of n Jobs through tw eory & Inventory Co- inology, Arrival Patto irth & Death Process Times with infinite ar	hod; Special Problem – For nan problem. ing nes, the max m eduction by pri flow shop sch o machines, I ontrol ern, Service Cl , Single Chann d finite queue	Cases mulat in and nciple nedulir Process nannel iel Mo length	ation Method; – Unbalanced ion, Hungarian 10 Hrs l min max s of dominance, ng, Solution of sing of n Jobs 12 Hrs , Population, dels with n; Multichannel noth	
Transportation F Method for Solv UNIT - III Game theory: C principle. Games arithmetic, algeb Job Sequencing through m mach UNIT - IV Queuing Theor Departure Patter Poisson Arrivals Models with Poi	Problem, De ing Assigni Optimal solu s without sa raic methoo g: Introduct Problem, H ines, graphi y: Introduct n, Queue D , Exponenti sson Arriva	and graph ion to Job s rocessing of cal method ueuing The ion – Term iscipline, B al Service T ls, Exponer	bution (MODI) Met roblem. Assignment ms, Traveling Salesm ory & Job Sequenci person zero sum gan mixed strategies. Re- ical method. shop Scheduling and of n Jobs through tw eory & Inventory Co- inology, Arrival Patto irth & Death Process Times with infinite ar atial Service Times w	hod; Special Problem – For nan problem. ing nes, the max m eduction by pri flow shop sch to machines, H ontrol ern, Service Cl , Single Chann d finite queue	Cases mulat in and nciple nedulir Process nannel nel Mo length eue ler	ation Method; – Unbalanced ion, Hungarian 10 Hrs 1 min max s of dominance, ng, Solution of sing of n Jobs 12 Hrs , Population, dels with n; Multichannel ngth.	

Inventory Control: Introduction, Deterministic models – EOQ model with and without shortages, Production model, Buffer stock and discount inventory models with single price breaks. Selective inventory control.

UNIT - V Replacement and Maintenance Analysis & DP 12 Hrs

Replacement and Maintenance Analysis: Introduction – Types of Maintenance, Make or buy decision. Types of Replacement Problems, Determination of Economic Life of an Asset, and Simple Probabilistic Model for Items which completely fail-Individual Replacement Model, Group Replacement Model.

Dynamic Programming (DP): Introduction –Bellman's Principle of Optimality –

Applications of Dynamic Programming – Shortest Path Problem – Capital Budgeting Problem Solution of Linear Programming Problem by DP

Course Outcomes (CO):

At the end of the course, the student will be able to

- Develop mathematical models for practical problems. (L3)
- Apply linear programming to transportation problems. (L3)
- Solve games using various techniques. (L3)
- Solve production scheduling and develop inventory policies. (L6)
- Apply optimality conditions for constrained and unconstrained nonlinear problems. (L3)
- Apply dynamic programming methods. (L3)

Textbooks:

- 1. Sharma S.D., Operations Research: Theory, Methods and Applications, 15/e, Kedar Nath Ram Nath, 2010
- 2. Taha H.A., Operations Research, 9/e, Prentice Hall of India, New Delhi, 2010.

- 1. Hiller F.S., and Liberman G.J., Introduction to Operations Research, 7/e, Tata McGraw Hill, 2010.
- 2. Sharma J.K., Operations Research: Theory and Applications, 4/e, Laxmi Publications, 2009.
- Prem kumar Gupta and Hira, Operations Research, 3/e, S Chand Company Ltd., New Delhi, 2003.
- 4. Pannerselvam R., Operations Research, 2/e, Pentice Hall of India, New Delhi, 2006.
- Sundaresan.V, and Ganapathy Subramanian.K.S, Resource Management Techniques: Operations Research, A.R Publications, 2015.



			Indust	rial Automation		
Course Cod	le	L:T:P:S	Credits	Exam Marks	Exam Durati	ion Course Type
22A0336P		1: 0:2:0	2	CIE: 30 SEE:70	3Hours	SAC
Course Obj	ectiv	ves:				·
Introd	uce	basic concept	s and princi	ples of Industrial A	utomation.	
• Famili	ariz	e with fluid p	ower systen	ns circuits.		
Descri	be c	concepts of SO	CADA softw	vare		
• Explai	n th	e principles o	of PLC and 8	8085 microprocesso	or.	
Expos	e the	e students on	Mechatronio	CS.		
Syllabus					Г	Fotal Hours:42
Module 1:						12 Hrs
Design and te	sting	g of fluid pow	ver circuits t	o control		
Introduction	to F	luid power sy	stems, Sym	bolic representation	n of hydraulic	and pneumatic
components.						
Tasks:-						
1. Pneumatic	trair	er kit with Fl	RL Unit, Sir	gle acting cylinder	, push button.	
2. Pneumatic	trair	ing kit with I	FRL unit, Do	ouble acting cylind	er, manually ac	ctuated DCV.
3. Pneumatic	trair	er kit with Fl	RL unit, Dou	uble acting cylinder	, Pilot actuated	d DCV.
4. Pneumatic	trair	er kit with Fl	RL unit Dou	ble acting cylinder	, Double solen	oid actuated DCV,
DCV with ser	isor	/ magnetic re	ed.			
5. Hydraulic p	owo	er pack with p	oumps and p	ressure relief valve	•	
Module 2:						10 Hrs
1. Open	sour	ce SCADA se	oftware such	n as Free SCADA,	Open SCADA,	,
2. Indigo	SC	ADA Code S	ys Open sou	rce for PLC progra	mming and int	terfacing with real
time P	LC					
3. Delta	PLC	software – fi	ree ware and	l corresponding PL	C programmin	g software.
4. 8085 1	Micr	oprocessor T	rainer with l	Power Supply		
5. Traffic	c Li	ght Control S	ystem			
Module 3						10 Hrs
Mechatronics						
1.	Ex	periment on I	P, PI and PII	O Controller.		
2.	Sir	nulation of H	ydraulic Ac	tuation System.		
3.	Sir	nulation of Pi	neumatic Ac	tuation System.		
4.	Sir	nulation on S	tepper Moto	or.		
5.	Sir	nulation on L	ogic gates, o	decoders and flip-fl	ops.	

References:

- B. Gavali, S. A. Patil and A. R. Koli, "Technology-Based Learning system in Programmable Logic Controller Education," 2016 IEEE Eighth International Conference on Technology for Education (T4E), Mumbai, 2016, pp. 264-265.
- 2. Groover, Mikell, Fundamentals of Modern Manufacturing: Materials, Processes, and Systems, 2014.
- 3. Lamb, Frank. Industrial Automation: Hands On (English Edition). NC, McGraw-Hill Education, 2013. ISBN 978-0071816458



		Fract	ure Mechanics		
Course Code	L:T:P:S	Credits	Exam Marks	Exam Dura	tion Course Type
22A03H01	3: 1:0:0	4	CIE: 30 SEE:70	3Hours	НСС
Course Objecti	ves:				
• To familia	arize with the	basic concep	ots of fracture mech	nanics and its	applications
Syllabus					Total Hours:60
UNIT - I					12 Hrs
Introduction: Hi	story and ove	r view, fract	ure mechanics appr	roach to desig	gn, effect of material
properties on frac	ture.				
Fracture Mecha	nisms: Ductil	e fracture, cl	leavage, ductile-bri	ttle transition	n, intergranular
fracture, environr	nent assisted of	cracking.			
Linear Elastic I resistance. R cury	Fracture Med	chanics: Gri unstable cra	iffith energy balan ck growth.	ce, energy r	elease rate, crack
UNIT - II					12Hrs
stress function , relation between	crack tip str stress intensit	ress field us y factor and	sing Westergaurd energy release rate	approach,effe	ect of finite size ,
UNIT - III					12 Hrs
Crack Tip Plas approach, shape o	stic Zone: P of the plastic z	lastic zone zone, plastic	shape, Irwin pla constraint factor, tl	stic zone conickness effection	orrection, Dugdale ct.
UNIT - IV					12 Hrs
Elastic-Plastic I relationships bety	Fracture Meet Network Meeting Sector Meeting Meeting Sector Meeting Sector Meeting Meeting Sector Meeting Meeting Sector Meeti	chanics: Cra OD, crack-s	ack-tip-opening dia growth resistance c	splacement, . urves, <i>J</i> contro	J contour integral, olled fracture.
UNIT - V			-		12 Hrs
Test Methods : Introduction, KIc-test technique, test methods to determine JIc,test methods to determine GIc AND GIIc, determination of critical CTOD. Crack Detection Through Non-Destructive Testing : Introduction, examination through human senses, liquid penetration inspection, ultrasonic testing, radiographic imaging, magnetic					
particle inspectio	n.		-		
Textbooks:					
1. T. L. And edition	erson, Fractur	e Mechanics	s: Fundamentals an	d Application	ns, CRC Press, 3rd
2. Prashant l edition.	Kumar, Eleme	ents Of "Frac	cture Mechanics, M	lcgraw Hill E	ducation, First

- 1. David Broek, Elementary engineering fracture mechanics, Kluwer Academic Publishers, 4th edition
- 2. J.F. Knott, P Withey, Worked examples in Fracture Mechanics, Institute of Materials, 2nd Edition

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GEETHANJALI INSTITUTE OF SCIENCE AND TECHNOLOGY (AUTONOMOUS)

NELLORE – 524137 (A.P) INDIA Computational Fluid Dynamics

		Computati	onai i iulu Dynamix			
Course Code	L:T:P:S	Credits	Exam Marks	Exam Dura	ation	Course Type
22A03H02	3: 1:0:0	4	CIE: 30 SEE:70	3Hour	5	HCC
Course Objecti	ves:		·			
To solve a	fluid flow/ hea	at transfer pr	oblems by the appl	ication of fin	nite di	fference and
finite volu	ume methods.					
Syllabus					Tota	al Hours:60
UNIT - I						12 Hrs
Governing equ	ations of fluid	d dynamics	and Heat Transfe	r: Models of	f the f	low, substantial
derivative, conti	nuity equation	n, the mome	ntum equation, the	energy equa	tion, i	nitial and
boundary condit	tions.					
Classification o	of partial Diff	erential Eq	uations: Introducti	on, Classific	ation	of partical
differential equa	ations - Crame	er's rule, Eig	en value method			
UNIT - II						12Hrs
Basic Aspects of	Discretizatio	n: Introduct	ion to Finite Differ	nece approa	ch, Di	fference
Equations. Finite	difference in	non-uniform	n grid, Types of erro	ors, consister	ncy, s	tability,
convergence. Sol	ution Techniq	ues for Syst	em of Algebraic Ec	quations: Dir	ect M	ethods,
Cramer's rule, m	atrix inversior	n, Gaussian e	elimination, Tri-dia	gonal matrix	algo:	rithm
(TDMA). Iterativ	ve method: Ga	uss-Jacobi. (Gauss -Seidel.			
UNIT - III		,				12 Hrs
Scheme.	fusion equatio	on - Explicit	Scheme, Crank-N	icolson Scer	ieme,	Fully Implicit
UNIT - IV						12 Hrs
Finite Volume dimensional stea scheme, Crank-N	Method for D ady state diffu ficolson schen	Diffusion Prosion, one din ne, fully imp	oblems: Finite volu mensional unsteady ilicit scheme	ume formula v diffusion: E	tions t Explic	for one it
UNIT - V		, , , ,				12 Hrs
Finite Volume	⊥ Method for C	Convection a	and Diffusion Prol	olems: Finite	e volu	me formulation
for steady one-d	imensional co	nvection an	d diffusion, the cen	tral differen	cing s	cheme,
properties of dis	cretisation scl	hemes, upwi	nd differencing		U	-
scheme.		× 1	e			
Course Outcom						
Linen successful	es(CO):	the course	the students will be	alla ta		
• Develop	completion of	the course,	uid flow and heat tr	caule to	locaifi	y the
• Develop §	forential aqua	tions	and now and near u		185511	y the
• A dont has	tic space and t	ime finite di	fference discretized	ion technicu	100 000	d
- Auapi das	she space and t		nterence discretisal	hnianaa	ics all	u
• Solve algo	ito difformatio	approach to	solvo ono dimensio	mil standar -	ndre	standy
Diffusion	problems.	approach to	Solve one dimensio	mai steauy a	na un	Sicauy

- Apply finite volume method for solving one dimensional steady and unsteady Diffusion problems.
- Solve one dimensional convection and diffusion problems using finite volume Method.

Textbooks:

- 1. John D. Anderson, J R "Computational fluid dynamics The basic with applications", Mc Graw Hill international, 2012.
- 2. H. Versteeg, W Malalasekra, "An Introduction to Computational Fluid
- 3. Dynamics The finite volume method", Pearson Publishers, 2nd Edition, 2018.

- 1. T. J. Chung "Computational fluid dynamics", Cambridge university press, 2003
- 2. Suhas V. Patankar, "Numerical heat transfer and fluid flow" Butter-worth Publishers
- **3.** T. K Sengupta, "Fundamentals of Computational Fluid Dynamics", University Press, 2013.



GEETHANJALI INSTITUTE OF SCIENCE AND TECHNOLOGY (AUTONOMOUS)

NELLORE – 524137 (A.P) INDIA Analysis and Synthesis of Mechanisms

Course Code	I.T.D.C	Chadita	From Moules	Evon Dure	tion	Course True	
	L:1:P:5		CIE: 20 SEE 70	Exam Dura	uon	Lourse Type	
22A03H03	3: 1:0:0	4	CIE: 30 SEE:70	3Hours		нсс	
Course Objectiv	ves:						
To impart	the concepts	of force anal	lysis of mechanism	s.			
To familia	rize with the	concepts of	synthesis of mecha	nisms.			
To impart	hands on train	ning on anal	ysis and synthesis	of mechanisn	ns usi	ing software	
packages							
Syllabus					Tota	l Hours:60	
UNIT - I	An	alysis of Co	omplex mechanisn	ns		12 Hrs	
Goodman indirec	t method and	Hall Ault au	xiliary point metho	od			
Dynamic Force	Analysis: D	Alembert pr	inciple , dynamic a	nalysis of fou	ur bar	mechanism	
and single slider	crank mechan	nism – dyna	mically equivalent	system – iner	rtia o	f Connecting	
Rod – inertia for	ce and torque	in reciproca	ating Engine.				
UNIT - II		Path Cur	vature Theory			12Hrs	
Introduction, fixed and moving centrodes, inflection points and inflection circle, Euler Savary Equation, Bobilliers Construction, Collineation axis, Bobillier theorem, Hartmann construction							
UNIT - III		Kinema	atic Synthesis			12 Hrs	
Introduction, type, dimensional and number Synthesis ,synthesis for function generation, path and motion generation, Chebyschev Spacing of accuracy points Motion Generation: Motion generation for two prescribed positions and three prescribed positions – path generation for three prescribed positions without and with prescribed timing – function generation for three prescribed positions, Poles and relative poles, relative poles of							
4-bar mechanism,	, relative poles	s of slider cr	rank mechanism.				
UNIT - IV	<u> </u>	Coup	oler Curves			12 Hrs	
Equation of coupler curves, synthesis for path generation, graphical synthesis for path generation, Robert-Chebyshev theorem (cognate linkages), coupler curves from 5-bar mechanisms. Analytical Synthesis Techniques: Four bar and slider crank function generator with three							
accuracy points,	Freudenstein	equation.		-			
UNIT - V		Manipula	tor Kinematics			12 Hrs	
Manipulator kiner	matics, positio	on represent:	ation, forward and	inverse transf	forma	ations,	
homogeneous tran a robot controller	nsformations, , robot joint co	manipulator	r path control, robo n.	t arm dynami	ics, co	onfiguration of	

Upon successful completion of the course, the students will be able to

- Determine the displacement, velocity and accelerations of links of mechanism.
- Evaluate the forces and torque acting by performing force analysis.
- Apply path curvature characteristics in analysis of mechanisms.
- Apply synthesis techniques in design of mechanisms. Analyze and synthesize mechanisms using software packages

Textbooks:

- 1. Erdman and Sandor , "Advanced Mechanism Design ",Prentice Hall International, 2nd Edition
- 2. S.S. Rattan, "Theory of Machines", Tata Mc Graw Hill, 3rd Edition
- 3. JJ Craig, "Introduction to Robotic Mechanisms and Control", Pearson, 3rd Edition.
- 4. Eric Constans and Karl B. Dyer, "Introduction to Mechanism Design With Computer Applications", CRC Press,1st Edition, 2019

- 5. Uicker, Pennock and Shigley, "Theory of machines and Mechanisms", Oxford Univ Press.
- 6. Amitabha Ghosh and Ashok Kumar Mallik, "Theory of Mechanism and machines", East West Press pvt Ltd, 2nd edition.
- 7. Robert L.Norton," Design of Machinery", Tata McGraw Hill, 3rd edition.



GEETHANJALI INSTITUTE OF SCIENCE AND TECHNOLOGY (AUTONOMOUS)

NELLORE – 524137 (A.P) INDIA Applications of Optimization Techniques

				iniques		
Course Code	L:T:P:S	Credits	Exam Marks	Exam Durat	ion Course T	Гуре
22A03H04	3: 1:0:0	4	CIE: 30 SEE:70	3Hours	HCC	
Course Objecti	ves:		,		I	
Explain p	rinciples of op	timization a	and its need.			
• Familiarization with theory of optimization methods and algorithms developed for						
solving va	arious types of	optimizatio	on problems.	-	-	
• Understar	id the mathem	atical found	ations for Genetic	Algorithm, Op	perators.	
Know fun	damental theo	ory and conc	epts of neural netw	orks, neuro –	modelling, sev	/eral
neural net	work paradigr	ns and its ap	oplications.		-	
Identify th	ne application	of optimiza	tion to design of ma	achine elemen	ts.	
Syllabus				r	Fotal Hours:6	0
UNIT - I		Int	roduction		12 Hrs	
Classical Optimi	zation Techn	iques: Sing	le variable optimiza	ation with and	without	
Constraints, Mult	i – Variable O	P timization	without constraints	s, Multi – Var	iable Optimiza	ition
with Constraints -	– Method of L	agrange Mu	ltipliers, Kuhn-Tuo	ker Condition	18.	
Numerical Meth	ods for Optin	nization: In	terval Halving Met	hod, Fibonaco	vi Method,	
Quadratic Interpo	lation Method	l, Newton M	Iethod, Quasi Newt	on Method, S	ecant Method.	
UNIT - II		Genetic A	Algorithm (GA)		12Hrs	
Differences and S	Similarities bet	tween Conv	entional and Evolu	tionary Algori	thms, Working	Б
Principle, Reprod	uction, Crosse	over, Mutati	on, Termination Cr	iteria, Differe	nt Reproductic	on
and Crossover Op	perators, GA f	or Constrair	ned Optimization, E	Praw Backs of	GA.	
UNIT - III		Genetic Pr	ogramming (GP)		12 Hrs	
Principles of Gen	etic Programn	ning, Termi	nal Sets, Functional	Sets, Differe	nces between (GA
& GP, Random P	opulation Gen	neration, Sol	ving Differential E	quations using	g GP.	
UNIT - IV		Neura	al networks		12 Hrs	
Introduction to 1	Neural netwo	rks: Knowl	edge base informat	ion processing	g, General Viev	w of
Knowledge Base	d Algorithm, N	Neural Infor	mation Processing,	Hybrid Intelli	gence and	
Artificial Neuron	s.					
Characteristics	of Artificial N	leural Netw	orks: Single Neura	ıl Networks, N	/Iulti – Layer	
Neural Networks	, Training of A	ANN – Obje	ctive, Supervise Tr	aining, Unsup	ervised Trainin	ng,
Overview of train	ling.					
UNIT - V	Applica	tions of Op	timization in Desi	gn and	12 Hrs	
		Manufac	turing Systems			
Some typical app	lications like (Optimization	n of Path Synthesis	of a Four – ba	ar Mechanism,	
Minimization of	Weight of a Ca	antilever Be	am, Optimization of	of Springs and	Gears, Genera	ıl
Optimization mod	del of a Machi	ining Proces	s, Optimization of	Arc Welding	Parameters and	1
General Procedur	e in Optimizir	ng Machinin	ng Operations Seque	ence.		

Textbooks:

- 1. Singiresu S. Rao, Engineering Optimization, 3/e, New Age Publishers, 2010.
- 2. Bart Kosko, Neural Networks and Fuzzy System, 2/e, Prentice Hall of India, 2001.
- 3. Goldberg D.E., Genetic algorithms in Search, Optimization, and Machine learning, 4/e, Pearson, 2009.
- 4. Kalyanmoy Deb, Optimization for Engineering Design: Algorithms and Examples, 2/e, PHI Learning Pvt. Ltd., 2012

- 1. Kalyanmoy Deb, Multi Objective Optimization using Evolutionary Algorithms, 1/e, John Wiley and Sons, 2001.
- 2. Jasbir S. Arora, Introduction to Optimum Design, 4/e, Academic Press, 2016.
- 3. Ravindran A., Engineering Optimization Methods and Applications, 2/e, John Wiley and Sons, 2006.
- 4. Fox R.L., Optimization Methods for Engineering Design, 1/e, Addison Wesley PublicationCo., 1971